MICROGUARD® 434/500
RATED CAPACITY LIMITER SYSTEM

TROUBLESHOOTING
MANUAL

GREER COMPANY

The Greer Company

The Greer Company is dedicated to the design and manufacture of electronic parts created to aid in crane operation and in the protection of crane operators and associated personnel. The following manual has been developed to assist in helping Service Personnel to understand, locate, and identify problems that may arise during the operation of the MicroGuard®434/500 Rated Capacity Limiter System. Persons using this Manual must be familiar with this System and with Electrical Servicing. Use of calibration routines without consultation with the Greer Company invalidates the warranty.

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MICROGUARD ®434/500
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SECTION 1 OVERVIEW & PREPARATION

This Troubleshooting Manual for the MicroGuard® 434/500 Rated Capacity Limiter System, manufactured by the Greer Company and installed on Link-Belt Construction Equipment Company (LBCE) cranes, provides information and methods for isolating problems that may arise during operation of the System. Some of these problems can be corrected in the field. Other problems may require replacement of parts or a return of a part to the factory for servicing. Service personnel should have prior training and experience in the procedure for operation and setup of this System.

The procedures in this manual, where possible, are based on crane operation and function. A basic tool kit consisting of wrenches and screwdrivers (flat and Phillips' blades) will be required to remove covers and units for inspection. A digital multimeter (DMM) may be required. The DMM must be capable of measuring DC voltage with a range of 0 volts to ± 50 volts and resolution of 0.1 volts. Resistance range is 0 ohms to 2 megohms. Low cost analog meters are not appropriate since the input impedance of these meters can give false readings.

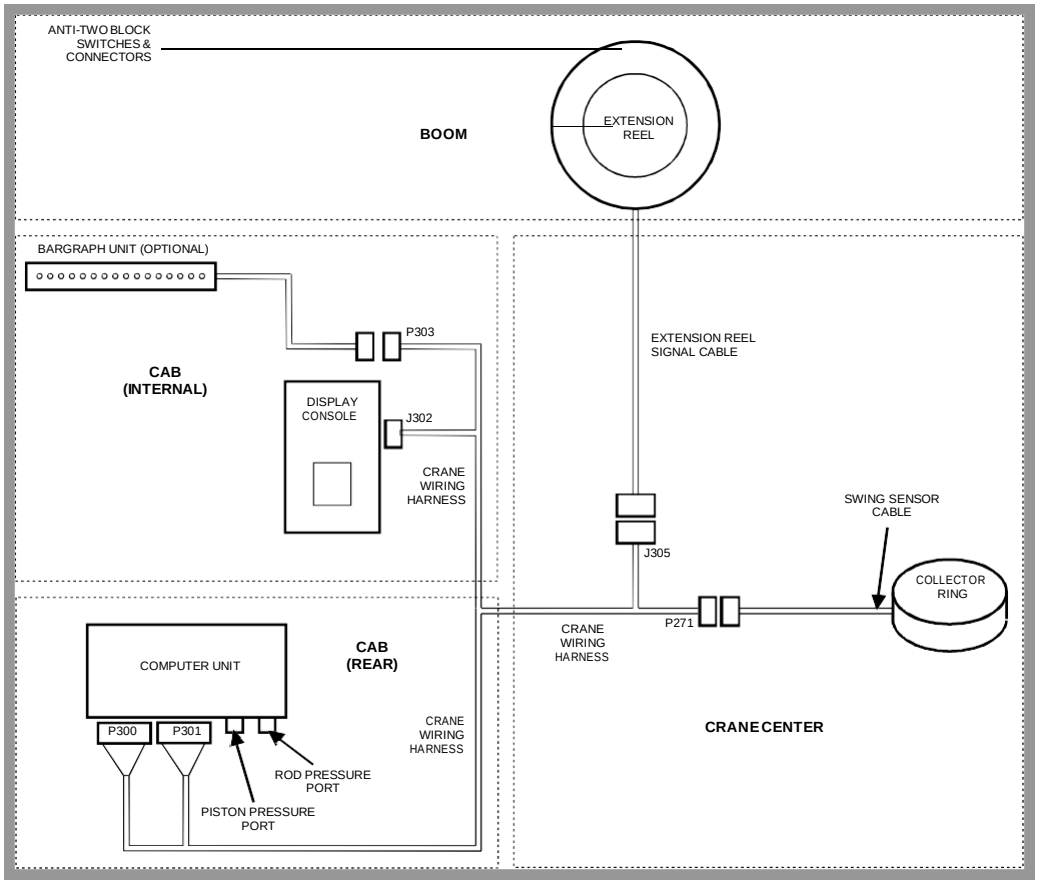

FIGURE 1.1 SYSTEM SCHEMATIC OVERVIEW

SECTION 2 PROBLEM FINDER

This PROBLEM FINDER section is designed to aid in determining the location and type of problem experienced. It is important to follow the recommendations within this section before contacting the Greer Company.

SYSTEM SELF-TEST

When the power is turned on or when the ”TEST” button is pressed during operation, the computer and operator’s display console perform a "SELF-TEST," which, as far as is possible, verifies that the computer, display console, cables, and all remote sensors are working properly.

During SELF-TEST, all display functions are activated, allowing the operator to check whether or not all indicators are functional.

NOTE: It is important that the indications shown during the SELF-TEST are recognized and fully understood by the operator in order to aid in correctly determining computer and display communication problems.

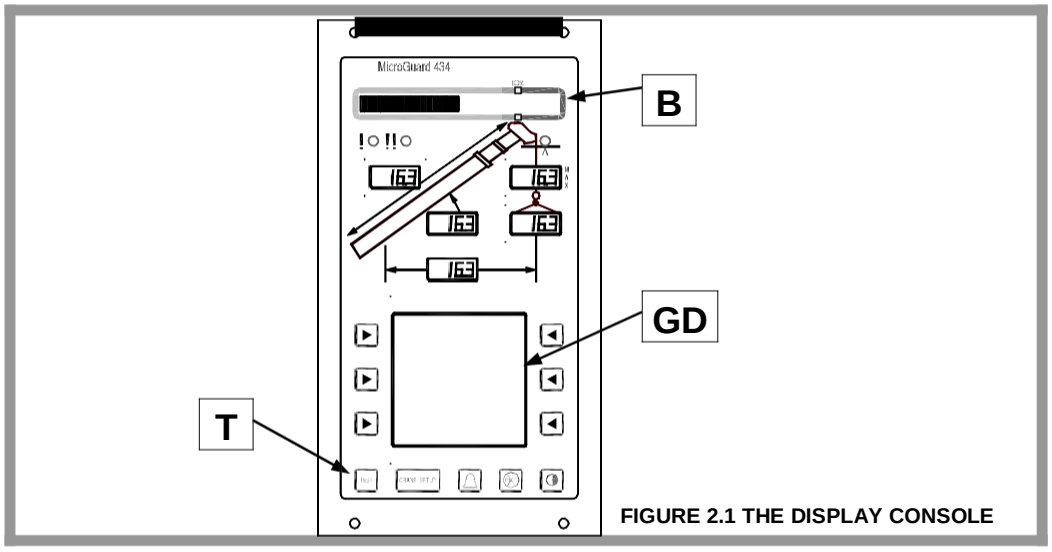

FIGURE 2.1 THE DISPLAY CONSOLE

For eight seconds following "power on" or activation of the TEST button (T), the display will show the following indications:

- All display segments of the bar graph display (B) will be black (ON).
- All display segments of the load, angle, radius, length, and rated capacity windows will be black (ON), showing “-i88.8”.
- The red LED indicators for overload and Anti Two-Block will be illuminated.
- The yellow LED indicator for pre-warning will be illuminated.
- The audible alarm will sound in the crane cab.
- The graphical display window (GD) will show “SYSTEM SELF-TEST IN PROGRESS” along with the crane model number and the Link-Belt Logo.

If any of the above indications do not occur, continue to SECTION 2.2 DISPLAY CONSOLE PROBLEMS.

DISPLAY CONSOLE PROBLEMS

DISPLAY CONSOLE PROBLEMS are difficult to isolate because of the interaction between the display console and the computer unit. Failure of either unit, or interconnection of the two units, causes malfunction of display console indications. No "FAULT" diagnoses of other system problems can be carried out without the proper function of the display console and it's communication with the computer unit.

To solve problems using display console indications, carefully observe the display console at "power on" and through self-test. Next, use the following chart to help decide the course of action.

PROBLEM	ACTION
There are no display console indications at all when power is turned on. All displays remain blank and no lights are illuminated.	Refer to SECTION 3.3.
The load, angle, radius, length, and rated capacity display windows do not show "-I88.8" or the bar graph display window has missing black segments during the self-test.	Replace display console.
The red or yellow indicator lights do not illuminate during self-test.	Replace display console.
The display console does not do the self-test. No words or logical numbers ever appear after power is turned on. The displays look jumbled, with lots of missing segments.	Replace display console.
The display console lights are lit. Load, angle, radius, length and rated capacity show "-I88.8", but the graphics display remains blank through and following the self-test.	Display console is OK. Check connectors at rear of display console. Refer to SECTION 3.4.

FAULT REPORTING AND FAULT CODES

SYSTEM FAULT CODES provide one of the most important ways to quickly locate and assess problems in the MicroGuard® System. Please review this section carefully.

Each time the system is turned on, it goes through a self-testing process lasting eight seconds that automatically detects most faults in the system. During normal operation, a self-test can be initiated at any time by pressing the TEST button on the display console.

Many fault conditions are detected without a system self-test.

Faults detected in the system during the self-test, are indicated on the display console in the following ways:

- The RED OVERLOAD LAMP will illuminate.
- The AUDIBLE ALARM will sound.
- "FAULT" will be displayed in the lower portion of the graphics display.

Fault codes may be displayed within the graphics display on the display console. To view the codes, press and hold the TEST button and wait for the system to complete the self-test. Do not release the TEST button. Fault codes will now be displayed in the lower portion of the graphics display, for as long as the TEST button is held down.

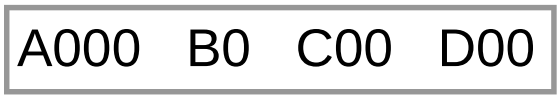

FIGURE 2.2 FAULT CODE DISPLAY SHOWN IN LOWER PORTION OF GRAPHICS DISPLAY

There are four groups of FAULT CODES: A,B,C & D. The function of these groups and a complete listing of each code is provided on the following pages.

NOTE
ALWAYS INVESTIGATE FAULTS IN THE "B" AND "C" GROUPS BEFORE CONTINUING WITH "A" AND FINALLY "D" GROUP FAULTS.

2.3.1 GROUP “A” FAULT CODES

GROUP “A” FAULT CODES REPRESENT FAULTS DETECTED FOR ANALOG SENSORS.

NOTE: CHECK AND REPAIR “B” AND “C” GROUP FAULTS **BEFORE** PROCEEDING WITH GROUP "A" FAULT FINDING SENSORS,

The following chart details all the available codes in the left column and the actions to take in the right column.

FAULT CODE	Swing Sensor	Boom Angle Sensor	Extension Sensor	Tdx 1 Rod Pressure	Tdx 0 Piston Pressure	ACTION
000	No Fault Found					NONE
001					X	Replace computer
002				X		
003				X	X	
004			X			Follow SECTION 6.4
005			X		X	Replace computer
006			X	X		
007			X	X	X	
008		X				Follow SECTIONS 6.6 through 6.8
009		X			X	Replace computer
010		X		X		
011		X		X	X	
012		X	X			Follow SECTION 6.3
013		X	X		X	Replace computer
014		X	X	X		
015		X	X	X	X	

GROUP "A" FAULT CODES continued

FAULT CODE	Swing Sensor	Boom Angle Sensor	Extension Sensor	Tdx 1 Rod Pressure	Tdx 0 Piston Pressure	ACTION
016	X					Follow SECTION 9
017	X				X	Replace computer
018	X			X		
019	X			X	X	
020	X		X			Follow SECTIONS 6.3, 6.4 & 9
021	X		X		X	Replace computer
022	X		X	X		
023	X		X	X	X	
024	X	X				Follow SECTIONS 6.7, 6.8 & 9
025	X	X			X	Replace computer
026	X	X		X		
027	X	X		X	X	
028	X	X	X			Follow SECTIONS 6.3, 6.4, 6.7, 6.8 & 9
029	X	X	X		X	Replace computer
030	X	X	X	X		
031	X	X	X	X	X	Follow SECTIONS 6.3, 6.4, 6.7, 6.8 & 9
032 & Higher	Internal Temperature Sensor Fault Replace Computer Unit					

GROUP "B" FAULT CODES

GROUP "B" FAULT CODES REPRESENT FAULTS DETECTED FOR INTERNAL ANALOG FUNCTIONS AND POWER FEEDS TO THE FUNCTION KICKOUT AND ANTI-TWO BLOCK SWITCHES.

The following chart details all of the available codes in the left column and the actions to take in the right column.

FAULT CODE	FKO POWER FEED	A2B POWER FEED	DISPLAY CONSOLE INTERNAL FAULT	ADC 2 INTERNAL FAULT	ADC 1 INTERNAL FAULT	ACTION
000	No Fault Found					NONE
001					X	Replace computer
002				X		
003				X	X	
004			X			
005			X		X	
006			X	X		
007			X	X	X	
008		X				See SECTION 7
009		X			X	Replace computer
010		X		X		
011		X		X	X	
012		X	X			
013		X	X		X	
014		X	X	X		
015		X	X	X	X	
016	X					Check crane circuit breakers, then See SECTION 3.5.1
017	X				X	Replace computer
018	X			X		
019	X			X	X	
020	X		X			
021	X		X		X	
022	X		X	X		
023	X		X	X	X	
024	X	X				Check crane circuit breakers, then See SECTION 3.5.1
25 X		X			X	Replace computer
26 X		X		X		
27 X		X		X	X	
28 X		X	X			
29 X		X	X		X	
30 X		X	X	X		
31 X		X	X	X	X	

GROUP "C" FAULT CODES

GROUP "C" FAULT CODES REPRESENT FAULTS DETECTED FOR INTERNAL COMPUTER MEMORIES.

FAULT CODE	SERIAL EEPROM	CRANE DATA	RAM	DUTY DATA	PROGRAM	ACTION
000	No Fault Found					NONE
001					X	Replace system chip Follow SECTION 3.5.2
002				X		
003				X	X	
004			X			Replace computer
005			X		X	Replace system chip Follow SECTION 3.5.2
006			X	X		
007			X	X	X	
008		X				Reset crane data
009		X			X	Replace system chip Follow SECTION 3.5.2
010		X		X		
011		X		X	X	
012		X	X			Replace computer
013		X	X		X	Replace system chip Follow SECTION 3.5.2
014		X	X	X		
015		X	X	X	X	
016	X					Reselect crane setup/configuration Replace computer, if not resolved
017	X				X	Replace system chip Follow SECTION 3.5.2
018	X			X		
019	X			X	X	
020	X		X			Replace computer
021	X		X		X	Replace system chip Follow SECTION 3.5.2
022	X		X	X		
023	X		X	X	X	
024	X	X				Reselect crane setup/configuration Reset crane data Replace computer, if not resolved
25 X		X			X	Replace system chip Follow SECTION 3.5.2
26 X		X		X		
27 X		X		X	X	
28 X		X	X			Replace computer
29 X		X	X		X	
30 X		X	X	X		
31 X		X	X	X	X	

GROUP "D" FAULT CODES

GROUP "D" FAULT CODES REPRESENT FAULTS DETECTED FOR CAPACITY CHART SELECTION.

The following chart details all the available codes in the left column and the actions to take in the right column.

FAULT CODE	WRONG SWING AREA	WRONG BOOM LENGTH	CHART NOT FOUND	ACTION
00	No Fault Found			NONE
01 X				Re-select CRANE SETUP. Check other sensor faults first.
002		X		Boom length is out of range for selected chart. Check crane setup, boom length and extension
003		X	X	Re-select CRANE SETUP. Check other sensor faults first.
004	X			Swing to correct working area to select chart. Check swing sensor zero position. Follow SECTION 9.5
005	X		X	Swing to correct working area to select chart. Check swing sensor zero position. Follow SECTION 9.5
006	X	X		Re-select CRANE SETUP. Check other sensor faults first.
007	X	X	X	Re-select CRANE SETUP. Check other sensor faults first.

"NO FAULT CODE" PROBLEMS

THIS SECTION ADDRESSES THOSE PROBLEMS THAT MAY OCCUR AND ARE NOT REPORTED BY THE COMPUTER FAULT CODE SYSTEM.

ANTI TWO-BLOCK ALARM (A2B)

This section gives direction to fault diagnosis of A2B alarm problems. For detailed information, schematic, and voltages, refer to SECTION 7 - ANTI TWO-BLOCK FUNCTION.

- **PROBLEM**

The Anti Two-Block alarm is continuously **ON**. Operating the switch at the boom head does not deactivate the alarm.

This problem suggests an open circuit between the computer A2B input and the A2B switch(es), or an open circuit between the computer A2B feed and the A2B switch(es)

1. Check extension reel-off cable for damage.
2. Make sure that the Two-Block switches are correctly connected.
3. Check the slip-ring and wiring inside the extension reel.
4. Check the signal cable from the extension reel to the computer. Check connectors (J305).

- **PROBLEM**

The Anti Two-Block alarm is continuously OFF (safe). De-operating the switch at the boom head, by lifting the A2B weight does not activate the alarm.

This problem suggests a short circuit between the computer A2B input and the computer A2B feed somewhere between the computer and the A2B switch(es).

1. Check extension reel-off cable for damage.
2. Make sure that the Two-Block switches are correctly connected.
3. Check the slip-ring and wiring inside the extension reel.
4. Check the signal cable from the reel to the computer. Check connectors (J305).

DISPLAYED LOAD OR RADIUS ERRORS

This section gives direction to fault diagnosis of load and radius errors as displayed on the display console. Load or radius errors may give rise to early or late tripping of overload alarms. Accuracy of load, radius, length, and angle is determined by the correct installation and maintenance of the system sensors.

Accuracy of load is governed by the radius accuracy, and the extension, angle, and pressure sensors.

Accuracy of radius (unloaded) is governed by the extension and angle sensors.

Before continuing, make sure that there are no system faults.

- **CHECK BOOM EXTENSION**

1. First check that the boom is fully retracted.
2. Check that the extension reel-off cable is correctly layered as a single layer across the extension reel surface. Any stacking of the cable will cause extension errors when the boom is fully retracted, causing the System to exceed the 0.5 ft tolerance allowed by the computer for boom mode selection. If the reel-off cable is stacking on the reel, see SECTION 6.2.
3. Check the zero of the extension sensor at the fully retracted boom position. Enter the Calibration Mode (SECTION 10.2). Using the “SPAN” command (SECTION 10.4.5), select sensor No. 2 to view the extension value in feet. The value of extension must be between -0.2 and +0.2, with the boom fully retracted. If the extension value is incorrect, follow the EXTENSION SENSOR SETUP procedure in SECTION 6.5.
4. Fully telescope the boom and check that the displayed boom length value matches the maximum length of the boom. If the length value is incorrect, follow the EXTENSION SPAN calibration procedure in SECTION 6.5.3 .

NOTE

The required accuracy of taped radius measurements is within 0.1 feet.

When taking radius measurements; always use a good quality tape that does not stretch. The tape should be graduated in feet and tenths of feet. Always measure between the swing center of the crane and the hook line, using a single part of line, with the crane centered over front (rough terrain crane) or centered over rear (truck crane).

- **CHECK MAIN BOOM RADIUS**

1. Fully retract the boom and make sure that the crane configuration is correctly set up.
2. Boom up to about 45° and measure the radius. The measured radius must match the displayed radius within +/- 0.2 ft. If it does **not** match, continue to the “CHECK BOOM ANGLE” procedure. If it does match, continue to “CHECK PRESSURE SENSORS.”
   Both procedures are on the next page.

NOTE

The required accuracy of measured angles is within 0.2°.

When taking boom angle measurements; always use a good quality inclinometer. Many inclinometers are only accurate at 0° (level). Make sure that a reliable position on the top of the boom is used to measure the angle and that the inclinometer will provide an accurate reading at 0° (zero) and at 70°.

- **CHECK BOOM ANGLE**

1. Fully retract the boom.
2. Using an inclinometer, set the boom to 0° (zero) and check that the displayed boom angle value is 0.0°. If the angle value is not 0.0°, follow SECTIONS 6.6, 6.9.1 and 6.9.2.
3. Boom up to a high angle (at least 70°) and measure the angle with the inclinometer. Check that the displayed angle matches the inclinometer reading within 0.2°. If the displayed angle is incorrect, follow the angle span calibration procedure in SECTION 6.9.3.

- **CHECK PRESSURE SENSORS**

The Pressure sensing system is factory calibrated, therefore pressure sensors may not be individually replaced. Any serious problems will necessitate changing the whole computer unit.

1. Boom fully down until the boom hoist cylinder is fully retracted and on its stop.
2. Loosen both hydraulic connections to the pressure sensors to guarantee *zero pressure is present* on the sensors.
3. Enter the CALIBRATION MODE (SECTION 10.2) and use the “PRESSURE MONITOR” command (SECTION 10.4.9) to view both sensor pressures and nett pressure.
4. Check the PRESSURE values of both sensors. The PRESSURE values should be between -75 and + 75 PSI. If not, replace the computer unit.
5. Check the NETT pressure. This should be between -35 and +35 psi. If not, replace the computer unit.

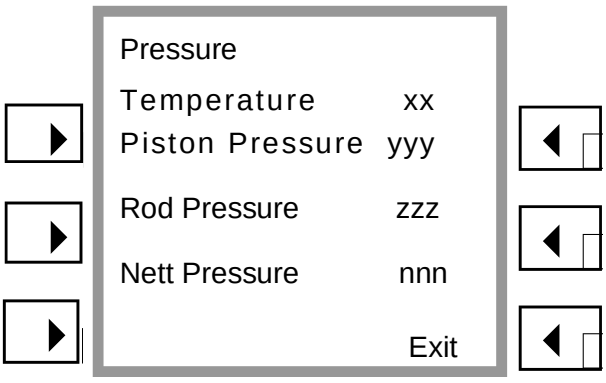

FIGURE 2.3 PRESSURE MONITOR

BOOM MODE SELECTION

This section gives direction to fault diagnosis of BOOM MODE selection problems.

The system provides an output from the computer, which drives a solenoid to power the boom telescope sequence in “A” or “B” modes. The System allows the operator to select either of the two modes only when the boom is within 0 to 0.5 ft of fully retracted.

- **IF “CRANE SETUP” DOES NOT ALLOW SELECTION OF A NEW BOOM MODE**

1. First check that the boom is fully retracted.
2. Check that the extension reel-off cable is correctly layered as a single layer across the extension reel surface. Any stacking of the cable will cause extension errors at fully retracted, which will exceed the 0.5 ft tolerance allowed by the computer for boom mode selection.
3. If the reel-off cable is stacking on the reel, go to SECTION 6.2.
4. Check the ZERO of the extension sensor at fully retracted. Enter the CALIBRATION MODE (SECTION 10.2) and use the “SPAN” command (SECTION 10.4.5). Select sensor No. 2 to view the extension value in feet. The value of extension must be between -0.2 and +0.2, with the boom fully retracted.
5. If the extension value is incorrect, follow the EXTENSION SENSOR SETUP procedures in SECTION 6.5.

SECTION 3 COMPUTER UNIT

The COMPUTER UNIT SECTION defines troubleshooting techniques and limited replacement procedures.

COMPUTER UNIT OVERVIEW

The COMPUTER UNIT, shown in Figures 3.1 and 3.2, is the center of the ***MicroGuard® 434/500*** System. The computer unit provides all the necessary functions to read the sensors, control computations, disconnect functions, and communicate with the display console/internal bar graph.

The computer unit directly connects to the crane wiring harness via a 60-way bulkhead connector. There are no wiring connections or screw terminals within the unit.

Contained within the unit, are the two hydraulic pressure transducers required to sense pressure within the boom hoist cylinder. These sensors and the computer are factory pre-calibrated and, as such, may not be separately replaced in the field.

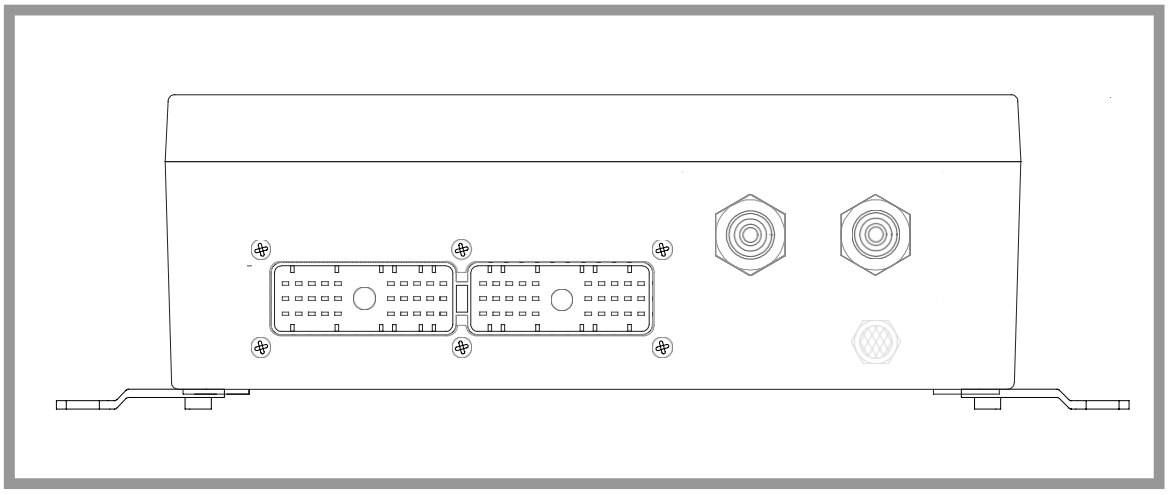

FIGURE 3.1 THE COMPUTER UNIT

COMPUTER UNIT LAYOUT

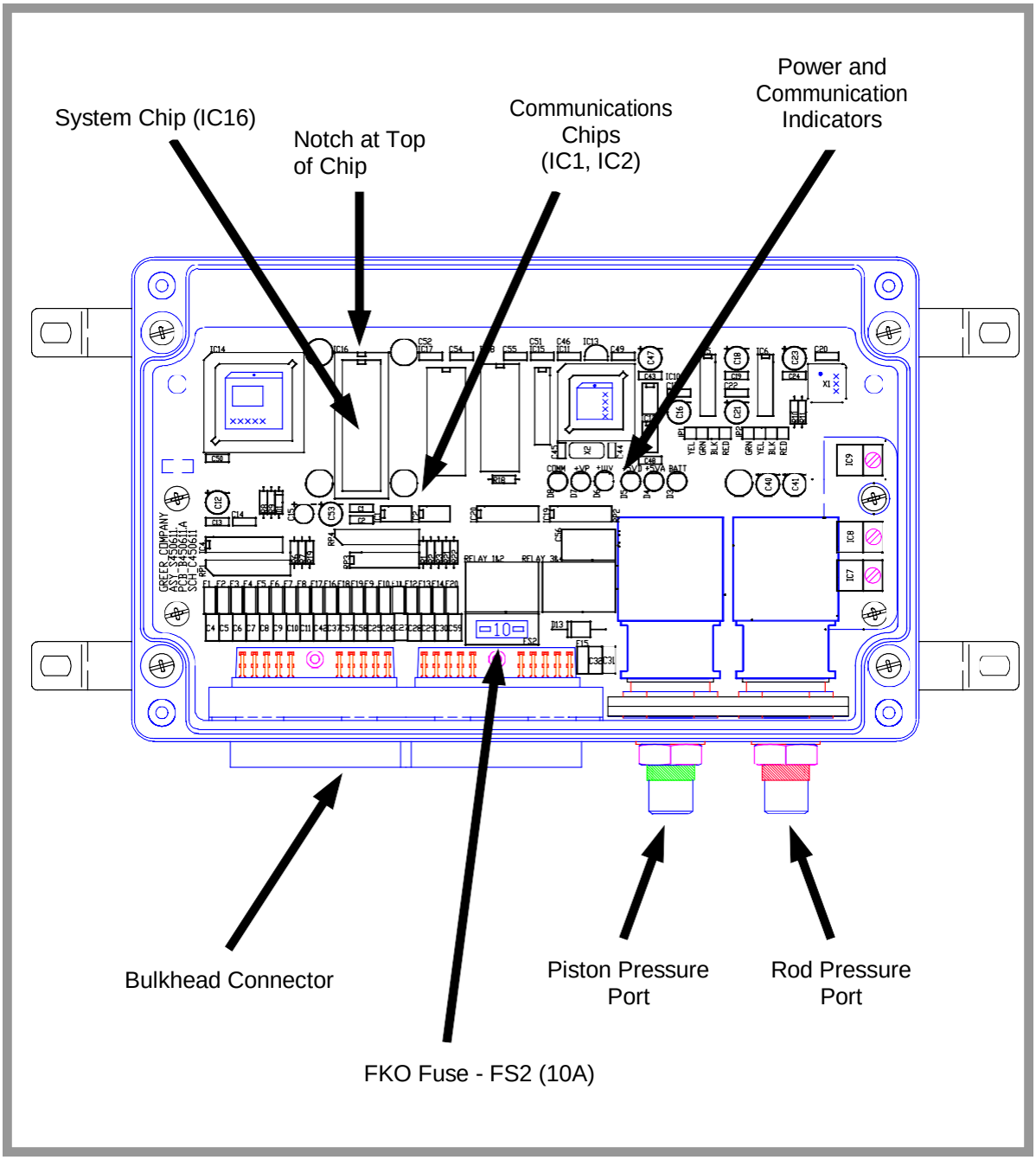

FIGURE 3.2 COMPUTER UNIT LAYOUT (LID REMOVED)

INTERNAL STATUS INDICATORS

The computer unit contains a row of indicators to aid in checking power supply and communications operation within the system. Remove the lid of the computer and check these indicators. Refer to the computer unit layout in Figure 3.2.

All the indicators are bright green light emitting diodes. There are five power indicators and one communication indicator (COMM). With the exception of the COMM indicator, all indicators should be illuminated at the same brightness level with the system power on.

A missing or dimly lit indication points to a power supply problem. Check the indicator chart below for repair actions.

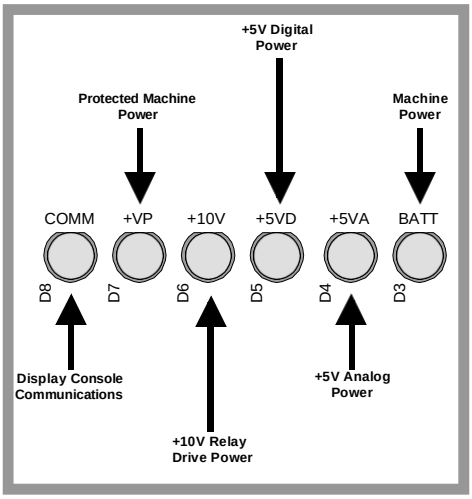

FIGURE 3.3 INTERNAL STATUS INDICATORS

Indicator states (● = Light OFF ○ = Light ON)	Actions
COMM +VP +10V +5VD +5VA BATT: ● ● ● ● ● ●	Check Crane power and circuit breaker.
COMM +VP +10V +5VD +5VA BATT: ● ● ● ● ● ○	+VP power to display console shorted to crane ground. Check display console/bargraph cabling.
COMM +VP +10V +5VD +5VA BATT: ○ ○ ● ○ ○ ○	+10V relay power internal short or regulator failure. Replace Computer.
COMM +VP +10V +5VD +5VA BATT: ● ○ ○ ● ● ○	+5VD digital power internal short or regulator failure. Replace Computer
COMM +VP +10V +5VD +5VA BATT: ○ ○ ○ ○ ● ○	+5VA analog power/drive to sensors. Check extension reel connection inside reel & wiring to extension reel.

FIGURE 3.4 INDICATOR STATES & ACTIONS

THE COMM INDICATOR

The COMM indicator provides an indication of the success or otherwise of communication with the display console, and of the running state of the computer program.

Carefully observe the COMM indicator and the display console at power on and through self-test; then, use the following chart to help decide the course of action.

See Figures 3.2 and 3.4 to locate the position of the COMM indicator.

COMM INDICATOR indications at power ON	ACTION
From the moment the power is applied, the COMM indicator does not illuminate. During and after the self -test period of eight seconds, the COMM indicator remains off.	The computer is not running. Check status indicators. See SECTION 3.3. Try to reset the system by powering off and on again. Listen to the computer for the relays to click. If they do not click, replace the system chip. If not successful, replace the computer. If the relays do click, replace communication chips IC1, 2. See SECTION 3.5.3.
From the moment system power is applied, the COMM indicator flashes at a fast rate and never stops. The display console never goes to normal display and displays "-I88.8" in the number display windows.	Communication with the display has not been made. Check connector at rear of the display console.
At the moment power is applied, the COMM indicator flashes briefly, then switches off. After a few seconds, the COMM indicator starts to flash at a fast rate and never stops.	This is the normal operation of the communication between the computer and display console. If there are any problems with indications on the display console, go to SECTION 2.2.

COMPUTER UNIT REPLACEABLE PARTS

The COMPUTER UNIT contains three parts that may be replaced in the field:

- A STANDARD 10 AMP AUTOMOTIVE FUSE, protecting the power feed to the function kickout circuit, is located on the circuit board within the unit.
- The system program/capacity chip, known as the SYSTEM CHIP (IC16).
- COMMUNICATIONS CHIPS (IC1, IC2) that communicate with the display console and are pluggable.

FUNCTION KICKOUT FUSE (FS2)

The computer unit contains a REPLACEABLE FUSE, illustrated in Figure 3.2, that protects the function kickout circuit and relay contacts, in the event that a short circuit across the crane kickout solenoids occurs.

The fuse, identified as FS2 on the computer board, may be replaced in the event that system error codes indicate that the function kickout power feed is missing, and it has been established that the crane circuit breaker is closed and power from the crane is present.

Before replacing the fuse, make sure that any electrical shorts that may have caused the failure of the original fuse have been removed.

WARNING

WHEN REMOVING AND INSTALLING THE FUSE, ENSURE THAT THE CRANE POWER IS TURNED OFF.

SYSTEM CHIP (IC16)

The computer unit contains a replaceable SYSTEM CHIP, illustrated in Figure 3.2.

The system chip, identified as IC16 on the computer board, contains program data, capacity charts and calibration data for the crane and is a 28-pin dual-in-line (DIL) device. This chip **MUST MATCH** the load chart in the crane. Installation of the system chip does NOT necessitate recalibration of the System, but under certain circumstances may require a "RESET CRANE DATA" operation (see SECTION 1.4.1) to be performed.

SYSTEM CHIP REMOVAL

1. Turn the power off.
2. Refer to Figure 3.2. Remove the chip from the computer board with a chip removal tool.

SYSTEM CHIP INSTALLATION

1. Use an installation tool to insert the new chip into the socket.
2. Ensure that the notch in the chip points to the upper side of the computer unit (opposite side to bulkhead connector and pressure ports.
3. Ensure that all pins are properly inserted into the chip socket. These pins are very easily bent.

WARNING

WHEN REMOVING AND INSTALLING CHIPS, ENSURE THAT THE POWER IS OFF. DO NOT TOUCH THE CHIP PINS UNLESS YOU ARE PROPERLY GROUNDED. STATIC ELECTRICITY CAN DAMAGE CHIPS.

ALWAYS USE A PROPER IC REMOVAL TOOL. USE OF SCREWDRIVERS, FINGERS, OR OTHER IMPLEMENTS MAY DAMAGE THE CHIP OR SERIOUSLY DAMAGE THE CIRCUIT BOARD. RECOMMENDED CHIP REMOVAL AND INSTALLATION TOOLS MAY BE OBTAINED FROM NEWARK ELECTRONICS STOCK NO. 10F7494 AND 10F7497.

FAILURE TO HAVE ALL PINS INSERTED PROPERLY INTO THE CHIP SOCKET MAY CAUSE DAMAGE TO THE SYSTEM AND THE CHIP.

COMMUNICATIONS CHIPS (IC1, 2)

The computer unit contains two replaceable COMMUNICATIONS CHIPS, illustrated in Figure 3.2.

The communications chips, identified as IC1 and IC2, on the computer board provide communication of data between the computer unit and display console (as well as bar graph unit, if fitted). These chips are pluggable and replaceable. Replacement of the communications chip does NOT necessitate recalibration of the System.

It is unlikely that the communications chips will become damaged, but in the event that the COMM indicator remains off at all times, changing these devices may provide a solution. See INTERNAL STATUS INDICATORS and the COMM INDICATOR in this section).

- **COMMUNICATIONS CHIPS REMOVAL**

  1. Turn the power off.
  2. Refer to Figure 3.2. Remove the chip from the computer board with a chip removal tool.

- **COMMUNICATIONS CHIPS INSTALLATION**

  1. Use an installation tool to insert the new chip into the socket.
  2. Ensure that the dot on the top of the chip is at the same corner as the IC1, IC2 legend on the circuit board.
  3. Ensure that all pins are properly inserted into the chip socket. These pins are very easily bent.

WARNING

WHEN REMOVING AND INSTALLING CHIPS, ENSURE THAT THE POWER IS OFF. DO NOT TOUCH THE CHIP PINS UNLESS YOU ARE PROPERLY GROUNDED. STATIC ELECTRICITY CAN DAMAGE THE CHIPS.

ALWAYS USE A PROPER IC REMOVAL TOOL. USE OF SCREWDRIVERS, FINGERS, OR OTHER IMPLEMENTS MAY DAMAGE THE CHIP OR SERIOUSLY DAMAGE THE CIRCUIT BOARD.

FAILURE TO HAVE ALL PINS INSERTED PROPERLY INTO THE CHIP SOCKET MAY CAUSE DAMAGE TO THE SYSTEM AND THE CHIP.

PRESSURE SENSORS

There are two PRESSURE SENSORS installed as part of a ***MicroGuard® 434/500*** System. Both pressure sensors are mounted within the computer unit and electrically connected to the computer board within. One is connected to the PISTON side of the boom hoist cylinder via a flexible hose; the other to the ROD side of the boom hoist cylinder via a flexible hose. Both hoses are protected by velocity fuses within the boom hoist cylinder valve block on the end of the cylinder(s).

The pressure sensor on the piston side is subject to the hydraulic pressure necessary to support the weight of the boom, any attachments, and the load. The other sensor monitors the pressure necessary to control down motion of the boom. The computer unit uses this information (along with that from other sensors such as extension, length, and angle) to compute the weight of the suspended load.

WARNING

Both pressure sensors are factory pre-calibrated and supplied as part of the computer unit. Removal or replacement of these devices from the computer invalidates the warranty and will adversely affect the pressure calibration.

The maximum continuous working pressure for these devices is 250 bar (3625 PSI).

- **CHECKING PRESSURE SENSORS**

The pressure sensing system is factory calibrated, therefore pressure sensors may not be individually replaced. Any serious problems will necessitate changing the whole computer unit.

1. Boom fully down until the boom hoist cylinder is fully retracted and on its stop.
2. Loosen both hydraulic connections to the pressure sensors to guarantee zero pressure is present on the sensors.
3. Enter the CALIBRATION MODE (SECTION 10.2) and use the "PRESSURE MONITOR" command (SECTION 10.4.9) to view both sensor pressures and nett pressure.
4. Check the PRESSURE values of both sensors. They should be between -75 and + 75 PSI. If not, replace the computer unit.
5. Check the NETT pressure. This should be between -35 and +35 PSI. If not, replace the computer unit.

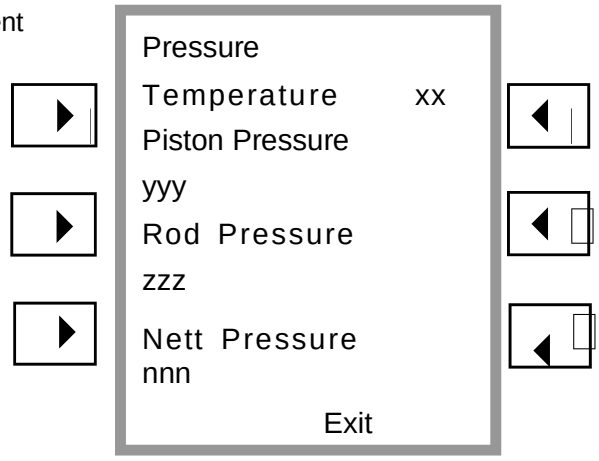

FIGURE 3.5 PRESSURE MONITOR

REPLACING THE COMPUTER UNIT

When changing the COMPUTER UNIT, it is strongly recommended that the SYSTEM CHIP be replaced at the same time. This ensures that the latest version of the chip is installed and guarantees that problems that may be caused by the existing chip are eradicated.

- **COMPUTER REMOVAL**

1. Boom down all of the way so that the boom hoist cylinder is fully retracted or the boom is firmly in the boom rest.
2. Disconnect hydraulic connections at the computer unit.
3. Note which hose is connected to the piston and rod pressure ports.
4. Disconnect both electrical connectors at the computer unit.
5. Remove the hardware securing the computer to the cab wall.

- **COMPUTER INSTALLATION**

1. Ensure that the correct system chip is installed in the computer.
2. Secure the computer unit to the cab wall with the mounting hardware.
3. Ensure that the electrical connections face downward.
4. Remove the two protective covers from the electrical bulkhead connector.
5. Connect the electrical connectors.
6. Remove the protective caps from the hydraulic ports.
7. Connect the base-side pressure hose to the piston pressure port.
8. Connect the rod-side pressure hose to the rod pressure port.

- **POWER UP AND CALIBRATION**

1. Switch the crane power on and check that all LED check lights within the computer unit are illuminated. Ensure that the COMMS LED is flashing and that the display console isoperating.
2. Enter the CALIBRATION MODE (SECTION 10.2).

To protect against unwanted data loss, which can occur during the SAVE or INITIALIZATION process, remember that it is possible to abort an action as long as it has not been finalized. A calibration has not been finalized until the operator gives the OK to calibrate.

3. Perform a CRANE DATA RESET (SECTION 10.4.1).
4. Fully retract the boom; using an inclinometer, set to zero degrees.
5. Calibrate the EXTENSION SENSOR ZERO (ZERO – sensor No. 2). See SECTION 10.4.2
   Calibrate THE ANGLE SENSOR ZERO (ZERO – sensor No. 3). See SECTION 10.4.3.
6. Boom up to a high angle and measure the angle with an inclinometer.
7. Calibrate the SPAN OF THE ANGLE SENSOR (SPAN – sensor No. 3).
   See SECTION 10.4.4.
8. Fully extend the boom.
10. Calibrate the SPAN of the EXTENSION SENSOR (SPAN – sensor No. 2).
    See SECTION 10.4.5
    NOTE: The SPAN is the fully extended boom length minus the fully retracted boom length, as specified in the capacity chart.
11. Fully retract the boom and ensure that the crane upper is set at the IN-LINE, OVER FRONT position with the house-lock engaged.
12. Calibrate the ZERO of the swing sensor (SWING – ZERO). See SECTION 10.4.6.
13. Release the house-lock and swing to the right, checking that the displayed swing value increases.
14. If the value reduces while swinging to the right, calibrate the swing direction (SWING – DIRECTION "-"). See SECTION 10.4.7.
15. Exit the CALIBRATION MODE and perform the checks that follow:

    CHECKS:

    - With an inclinometer, check the accuracy of the boom angle and the radius measurements and tape at four or five points.
    - Ensure that the hydraulic connections are secure and not leaking at the computer unit.
    - Secure the computer lid and rain cover.

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SECTION 4 DISPLAY CONSOLE

DISPLAY CONSOLE OVERVIEW

The OPERATOR'S DISPLAY CONSOLE (Figure 4.1) allows the user to see the crane values (angle, radius, load, etc.) and crane configuration selection. The display also provides calibration functions used for testing and fault diagnosis.

DISPLAY CONSOLE MODELS

There are two OPERATOR'S DISPLAY CONSOLE MODELS: The in-dash horizontal and in-dash vertical mounts. The consoles are identified by the LBCE PARTS MANUAL. Parts within the operator's display console cannot be serviced in the field.

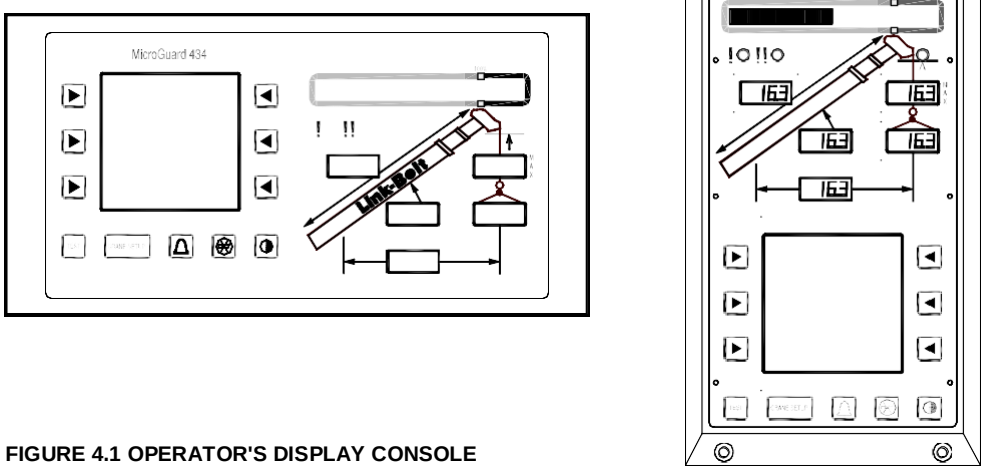


FIGURE 4.1 OPERATOR'S DISPLAY CONSOLE

CHECKING THE DISPLAY CONSOLE

The OPERATOR'S DISPLAY CONSOLE is normally very reliable. However, when operated for extended periods, under extreme conditions, the console can become damaged. The damage is not always apparent. To help identify subtle faults that are sometimes difficult to find, or that may be attributed, mistakenly, to other kinds of problems, please review the following comments.

READING THE (LIQUID CRYSTAL) DISPLAYS

Always adjust the display contrast first. On bracket-mounted models only, reposition the display console slightly. The most commonly encountered problem is caused by reflections.

NOTE: It may not be possible to correct this problem completely, especially on flush-mounted display consoles exposed to bright sunlight. If the problem concerns the contents of one or more of the display screens, refer to the PROBLEM FINDER FLOW CHARTS in SECTION 2 of this manual.

BUTTONS THAT DON'T RESPOND

All button options are not available for use at all times. Ensure that the non-responsive button is programmed to respond at that point in the operation of the System. Press the button in the center. Pressing the printed symbol 'at one end' may not activate the switch underneath. Buttons that are damaged or have a surface that is worn may cause the switch underneath to operate improperly. In this case, refer to OPERATOR'S DISPLAY CONSOLE – REMOVAL AND INSTALLATION.

CONNECTORS

A SINGLE CIRCULAR CONNECTOR, common to all display models, is positioned on the rear of the display console. On the bracket-mounted style, it is clearly visible on the rear of the housing. On the flush-mounted versions, it is 'hidden' behind the panel, within the dash assembly. This connector carries power and signals from the computer unit to the display console. Examine this connector carefully. It is possible for the pins and sockets within the connector halves to bend, break, or 'be pushed back' inside the housing.

On FLUSH-MOUNTED DISPLAY CONSOLES (VERTICAL MODEL), ONE ADDITIONAL CONNECTION, besides the circular connector, is required: The HORN DRIVE WIRE is a single black lead that should be attached to the black terminal on the rear of the display console housing.

HORN

On vertical FLUSH-MOUNTED CONSOLES, the HORN is outside the housing. If there is a problem with the horn, ensure that the HORN DRIVE WIRE is connected correctly to the black terminal on the rear of the display console housing. Release the display console from its connections and pull it gently forward. If the wire is intact and connected correctly and the horn is still not operating correctly, the horn may need to be replaced. If possible, test the horn operation by temporarily installing another horn known to operate correctly.

MOISTURE

The DISPLAY CONSOLES (BOTH BRACKET AND FLUSH-MOUNTED DESIGNS) offer adequate protection against dust and water, when correctly installed. However, they are unlikely to fully protect the sensitive electronic assemblies inside against pressure-washing or heavy rainfall. In this case, replace the console, especially if moisture is visible behind the display windows.

REPLACEMENT OF FLUSH-MOUNT CONSOLES

REMOVAL OF HORIZONTAL AND VERTICAL FLUSH-MOUNT CONSOLES

1. Remove and set aside the four mounting screws on the defective OPERATOR'S DISPLAY CONSOLE.
2. Disconnect the cable and horn wire (vertical units only) from the connector on the rear of the defective operator's display console.

INSTALLATION OF HORIZONTAL AND VERTICAL FLUSH-MOUNT CONSOLES

1. Attach the electrical cable and horn wire (vertical units only) to the electrical connector on the new console.
2. Attach the new OPERATOR'S DISPLAY CONSOLE to the cab with the four mounting screws.

REPLACEMENT OF BRACKET-MOUNT CONSOLES

REMOVAL OF HORIZONTAL BRACKET-MOUNT CONSOLES

1. Disconnect the electrical cable from the electrical connector on the rear of the OPERATOR'S DISPLAY CONSOLE.
2. Remove the defective operator's display console from the bracket in the cab by removing the knob on each side of the console. Retain the knobs for future use.

INSTALLATION OF HORIZONTAL BRACKET-MOUNT CONSOLES

1. Install the new OPERATOR'S DISPLAY CONSOLE on the bracket in the cab by positioning it between the bracket legs and inserting and tightening the knob on each side of the console.
2. Connect the electrical cable to the electrical connector on the rear of the console.

SECTION 5 REMOTE BAR GRAPH

REMOTE BAR GRAPH OVERVIEW

The REMOTE BAR GRAPH, shown below, displays the percentage of rated capacity of the crane. The remote bar graph is mounted at the top of the cab front window, in the operators line of sight. User-selectable levels of brightness are available on the device, which is designed for reading under all lighting conditions. Defective remote bar graphs cannot be serviced.

The remote bar graph is optional and is not used on all cranes.

FIGURE 5.1REMOTE BAR GRAPH

CHECKING THE REMOTE BAR GRAPH

The REMOTE BAR GRAPH is normally very reliable. However, when operated for extended periods, under extreme conditions, the device can become damaged. The damage is not always apparent. To help identify subtle faults that are sometimes difficult to find, or that may be attributed, mistakenly, to other kinds of problems, please review the following comments.

LAMPS

The 'LAMPS' are LIGHT EMITTING DIODES (LED's). They are more reliable than standard incandescent bulbs and consume far less power. LED operation can be checked at any time by the operator by pressing the test button on the operator's display console. Always replace the entire bar graph unit if it is found to be faulty.

With the System powered, there should always be at least one (GREEN) LED lighted – the one ***furthest*** from the BRIGHTNESS CONTROL push button, even when there is no load suspended. The REMOTE BAR GRAPH LED's should 'track' or 'echo' the bar graph on the operator's display console at all times.

BRIGHTNESS CONTROL

There are four levels of brightness. Holding the BRIGHTNESS CONTROL BUTTON continuously will cause the unit to automatically 'cycle' through the available levels. Release the button at any time to select the desired setting. Alternately pressing and releasing the button will cause the cycle to progress through the four levels in sequence. It is **not** possible to 'switch-off' the LED's using this control.

The currently selected brightness level is not stored within the ***MicroGuard***® System when the power is switched off. Therefore, the brightness desired will have to be set again manually when the System is next used. The remote bar graph always starts with the LED's set to MAXIMUM brightness.

CABLE AND CONNECTOR

The REMOTE BAR GRAPH uses a single cable to communicate with the computer unit and to carry power. The cable is nonremovable and is a fixed length. Excess cable should be stored (not discarded) when the unit is installed. Extending this cable is not recommended.

There is a single connector on the far end of this cable. This connector carries power and various signals between the computer unit and the remote bar graph. Because of the nature of connectors, it is possible for the pins and sockets within the connector halves to be damaged. A pin may be bent, broken, or 'pushed back' inside the housing.

MOISTURE

The REMOTE BAR GRAPH offers adequate protection against dust and water when correctly installed. It is not possible, however, to fully protect the sensitive electronic assembly inside against pressure-washing or heavy rainfall. If this occurs, the remote bar graph should be replaced.

REMOTE BAR GRAPH REPLACEMENT

- **REMOVAL OF REMOTE BAR GRAPH**

1. Turn off the power.
2. Remove the display console in order to access cabling in connectors.
3. Disconnect the remote bar graph cable from the display console wire harness at the rear of the display console.
4. Remove the remote bar graph from its bracket by loosening and removing the knob at each end of the remote bar graph. Retain the knobs for reuse.

- **INSTALLATION OF REMOTE BAR GRAPH**

1. Put the new remote bar graph in position. Reconnect and tighten the two knobs.
2. Route the cable to the display console and connect the cable.
3. Turn on the power and ensure that the remote bar graph operates correctly.

SECTION 6 EXTENSION REEL

EXTENSION REEL OVERVIEW

The primary operation of the EXTENSION REEL is to measure the extension of the telescoping sections of the main boom. The extension reel also includes an angle sensor to measure the main boom angle, and an electrical slip-ring which transfers the Two-Block signal from the reel-off cable to the system computer.

The extension reel is designed to provide a very accurate measurement of extension and angle. It is important that the setting up and maintenance of these devices be properly carried out as per the procedures contained within this manual. Incorrect maintenance will result in system calculation errors.

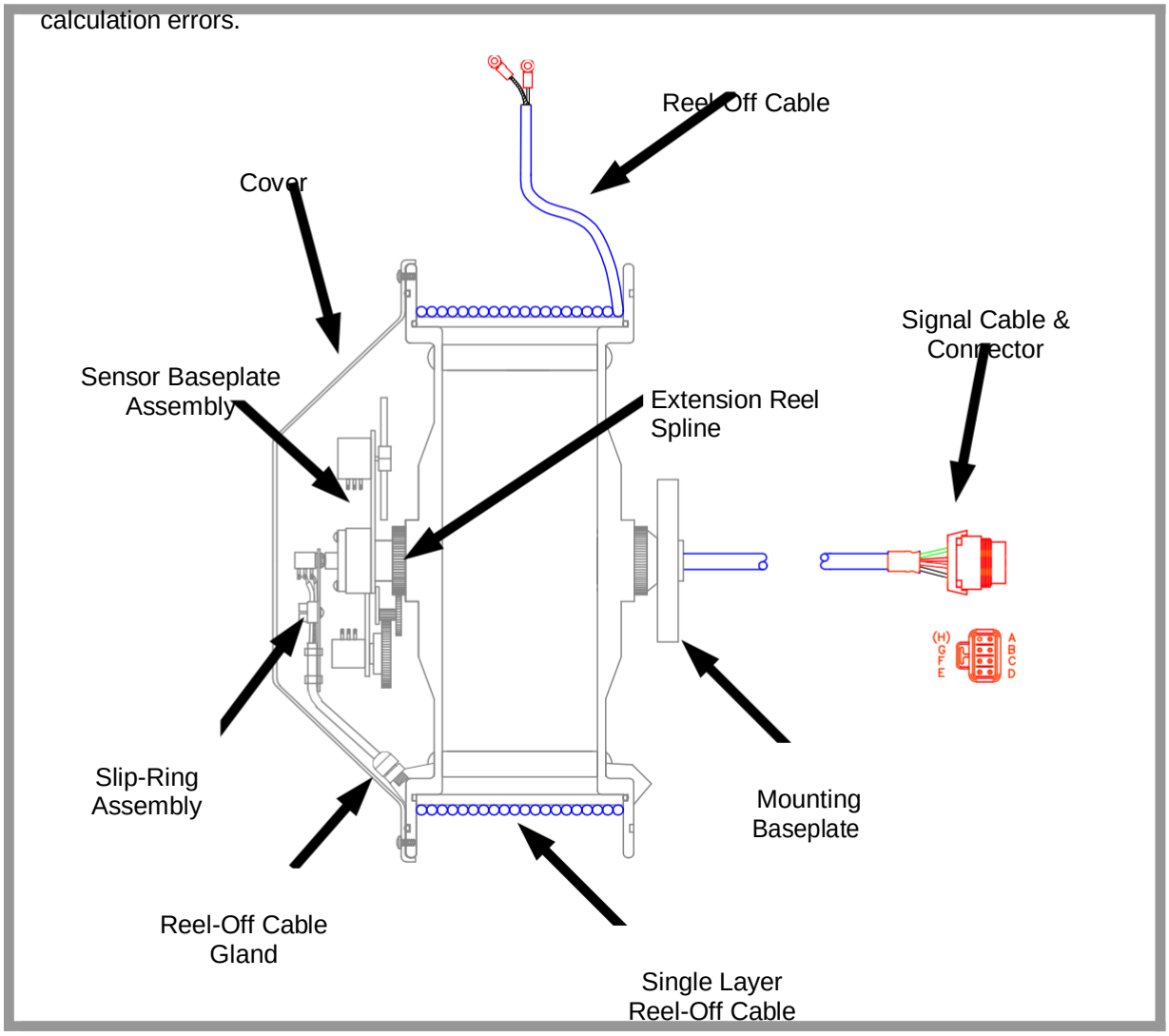


FIGURE 6.1 EXTENSION REEL CUT-AWAY DRAWING

CHECKING THE REEL-OFF CABLE LAYERING

The extension reel is designed to provide accurate measurement of boom extension when the REEL-OFF CABLE forms a single flat layer across the surface of the extension reel as the boom is telescoped in and out. Any stacking of the cable will cause extension [redacted] as the boom retracts.

1. Telescope the boom fully out and then fully in.
2. Check that the reel-off cable forms a flat single layer across the surface of the extension reel, with each successive turn of cable laying next to the last.

If any stacking or build up of the cable occurs, make sure that the first cable guide at the top of the boom root section is correctly aligned with the outside edge of the extension reel, as shown in Figure 6.2 below.

Clean the reel-off cable; then lubricate it with a silicone oil.

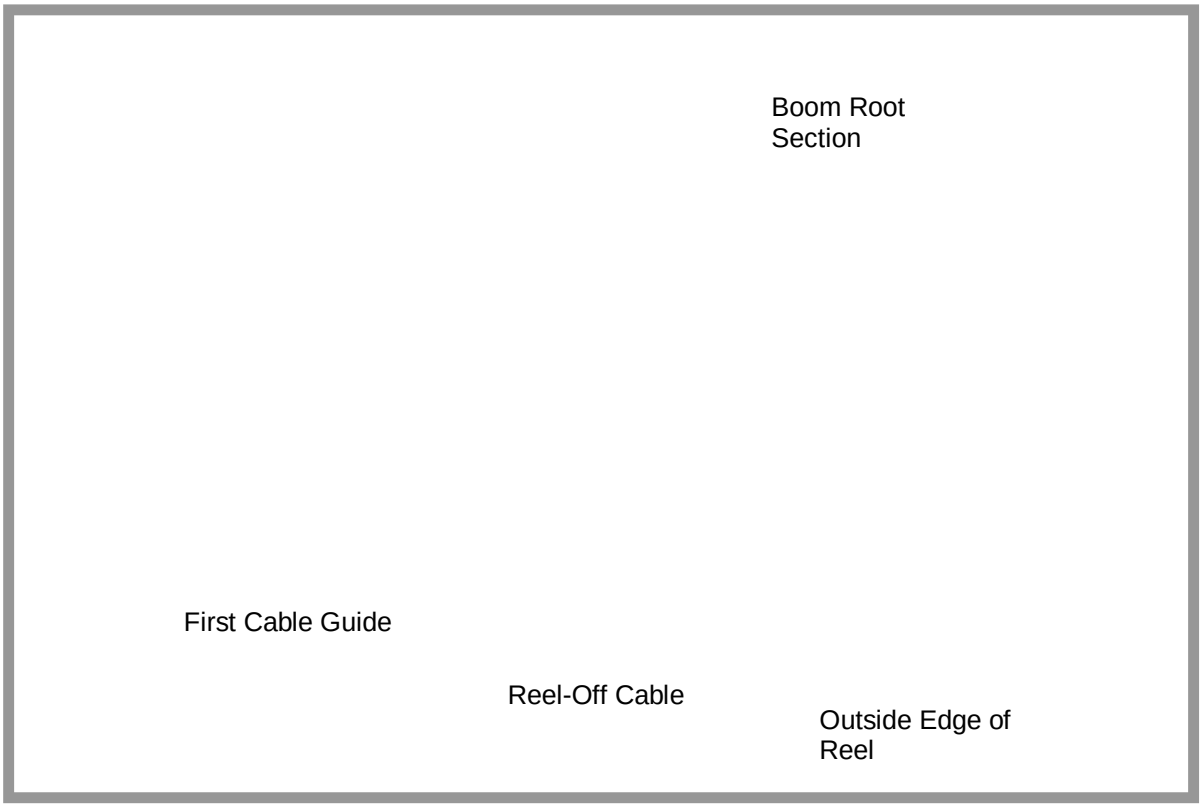


FIGURE 6.2 EXTENSION REEL VIEWED FROM ABOVE

CHECKING THE EXTENSION SENSOR DRIVE VOLTAGE

1. Remove the extension reel cover.
2. Using a digital voltmeter, measure the voltage between the RED (TB1-4) and BLUE (TB1-1) wires at the terminal block mounted on the sensor baseplate assembly.
3. Check that the voltage is between 4.7 and 5.3 volts.

Voltages outside the range specified above will indicate an interconnection problem between the extension reel and the computer or, a short circuit within the extension reel. Check extension reel wiring within the reel and at connector J305.

CHECKING THE BOOM EXTENSION SENSOR VOLTAGE

1. Fully retract the boom.
2. Remove the extension reel cover.
3. With a digital voltmeter, measure the voltage between the BLUE wire (TB1-1) and the WHITE wire (TB1-3).
4. With the boom fully retracted, the voltage should be between 0.1 and 0.3 volts. If the voltage is incorrect, follow the EXTENSION SENSOR SETUP PROCEDURE. (See next page.)
5. Still measuring the voltage at the same points, telescope the boom out and check that the potentiometer is operating by verifying that the voltage increases.

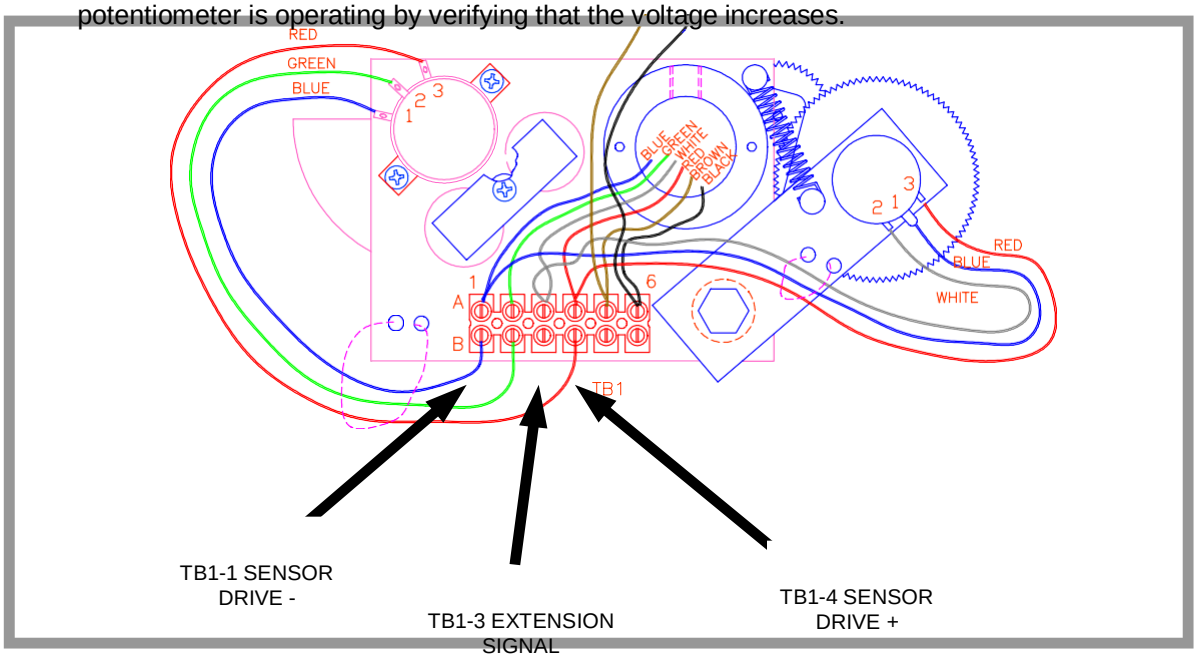


FIGURE 6.3 SENSOR BASEPLATE ASSEMBLY WIRING

EXTENSION SENSOR SETUP

The following procedures define how to reset and calibrate the EXTENSION SENSOR, if necessary. Before any of these procedures are used, check that the reel-off cable is layering correctly (SECTION 6.2).

PHYSICAL ZERO

It is necessary to ensure that the extension sensor potentiometer is correctly set to its minimum "zero" setting when the boom is fully retracted. This ensures that the sensor will correctly measure over the full telescoping range of the boom.

1. Fully retract the boom.
2. With the cover of the extension reel removed, disengage the main gear wheel connected to the extension sensor by pulling the sensor arm in the direction shown.
3. Rotate the gear clockwise until the sensors clutch detonate starts to click. At the next click, stop rotating the gear.
4. Measure the voltage between TB1-3 and TB1-1 (Figure. 6.3).

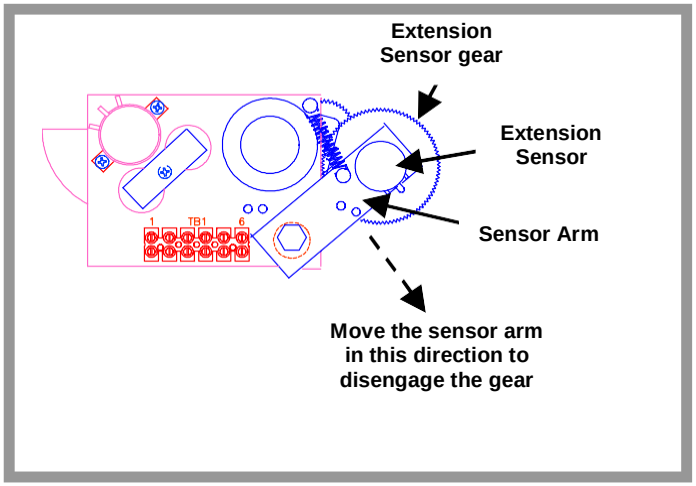


FIGURE 6.4 SENSOR ASSEMBLY

5. Rotate the gear counterclockwise about half a turn setting the voltage to 0.2 volts. Then, carefully release the sensor arm, ensuring that the voltage remains at 0.2 volts as the gears re-engage.

ZERO CALIBRATION

The computer must identify where the ZERO POINT of the extension sensor has been set (see above). It is therefore necessary to calibrate the zero setting of the potentiometer.
SEE SECTION 10.4.2.

Before continuing, ensure that the mechanical zero has been properly set. See SECTION 6.5.1.

1. Fully retract the boom.
2. Enter the calibration mode at the display console.
3. Select Command 02, SENSOR ZERO.
4. Select sensor No. 2.
5. Zero the extension sensor.
6. Before exiting the command, ensure that the displayed value is between -4 and +4.

SPAN CALIBRATION

The computer must be able to treat measurements of distance provided by the extension sensor. It is therefore necessary to calibrate the SPAN of the extension potentiometer. (See SECTION 10.4.5).

Before continuing, ensure that the calibration zero has been properly set, as described in SECTION 6.5.2 .

1. Fully extend the boom.
2. Enter the CALIBRATION MODE at the display console.
3. Select Command 03, SENSOR SPAN
4. Select sensor No. 2.
5. Calibrate the SPAN value, which is the fully extended boom length — (minus) the fully retracted boom length.
6. Before exiting the Command, check that the displayed value is within +/– 0.2 of the extension value calculated in No. 5 above.

CHECKING THE ANGLE SENSOR PENDULUM

The ANGLE SENSOR uses a copper PENDULUM, mounted behind the sensor assembly. In order to stop the pendulum from swinging uncontrollably during movements of the boom, two magnets provide damping.

If problems with the angle sensor are suspected, check that the pendulum and potentiometer are operating without restriction, before continuing to check electrical operation and performing any calibration.

1. Remove the extension reel cover.
2. Locate the PENDULUM. Refer to Figure 6.5 below.
3. Push the pendulum downwards in the direction shown and ensure that it doesn't feel as if it is sticking. Some resistance of movement may be encountered as the pendulum is moved; however, this is due to the magnets that provide the damping.
4. Release the pendulum and make sure that it returns with free, but controlled movement, directly back to its original position.
5. Push the pendulum downwards a few more times, checking that it returns, each time, to its starting position.

NOTE: If any "sticking" of the pendulum is encountered while performing the above checks, ensure that there are no wires touching the pendulum, or that other obvious problems are present. If not, it will be necessary to replace the sensor assembly.

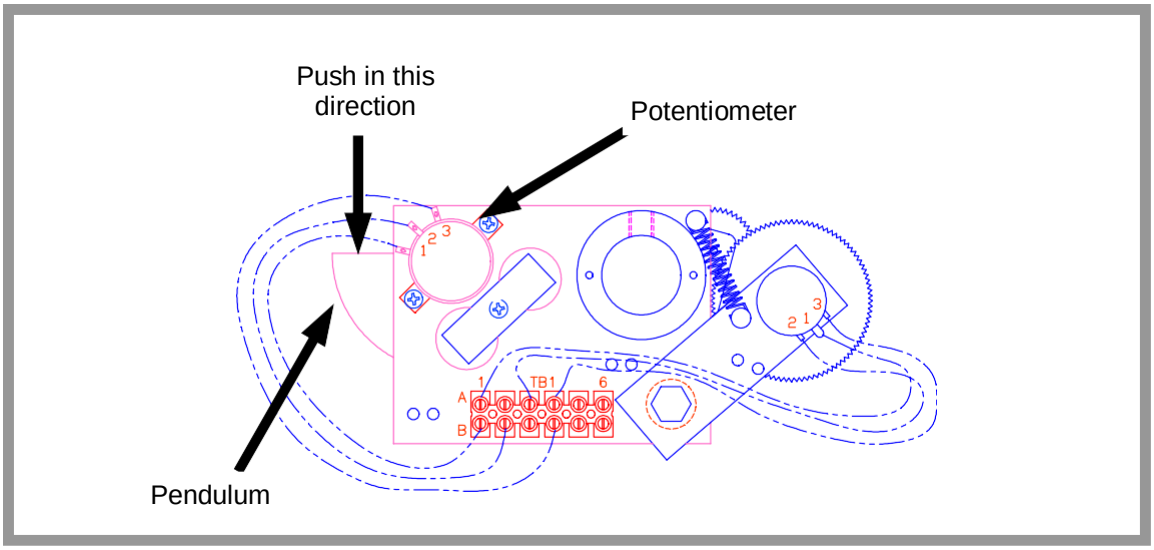


FIGURE 6.5 SENSOR ASSEMBLY

CHECKING THE ANGLE SENSOR DRIVE VOLTAGE

1. Remove the extension reel cover.
2. Using a digital voltmeter, measure the voltage between the RED (TB1-4) and BLUE (TB1-1) wires at the terminal block mounted on the sensor baseplate assembly.
3. Check that the voltage is between 4.7 and 5.3 volts.

Voltages outside the range specified above will indicate an interconnection problem between the extension reel and the computer or, a short circuit within the extension reel. Check extension reel wiring within the reel and at the boom foot base connector.

CHECKING THE ANGLE SENSOR VOLTAGE

4. Using an inclinometer for verification, place the main boom at a 0° (zero) angle; then remove the extension reel cover.
5. With a digital voltmeter, measure the voltage between the BLUE wire (TB1-1) and the GREEN wire (TB1-2). With the boom horizontal, the voltage should be between 0.3 and 0.5 volts. If the voltage is incorrect, follow the ANGLE SENSOR SETUP PROCEDURE.
6. Still measuring the voltage at the same points, move the exposed side of the angle sensor pendulum downwards, and check that the potentiometer is operating by verifying that the voltage increases.
7. Check that the pendulum moves freely, and when released, falls smoothly back to the original 0° (zero) voltage reading, as measured in Step 5.

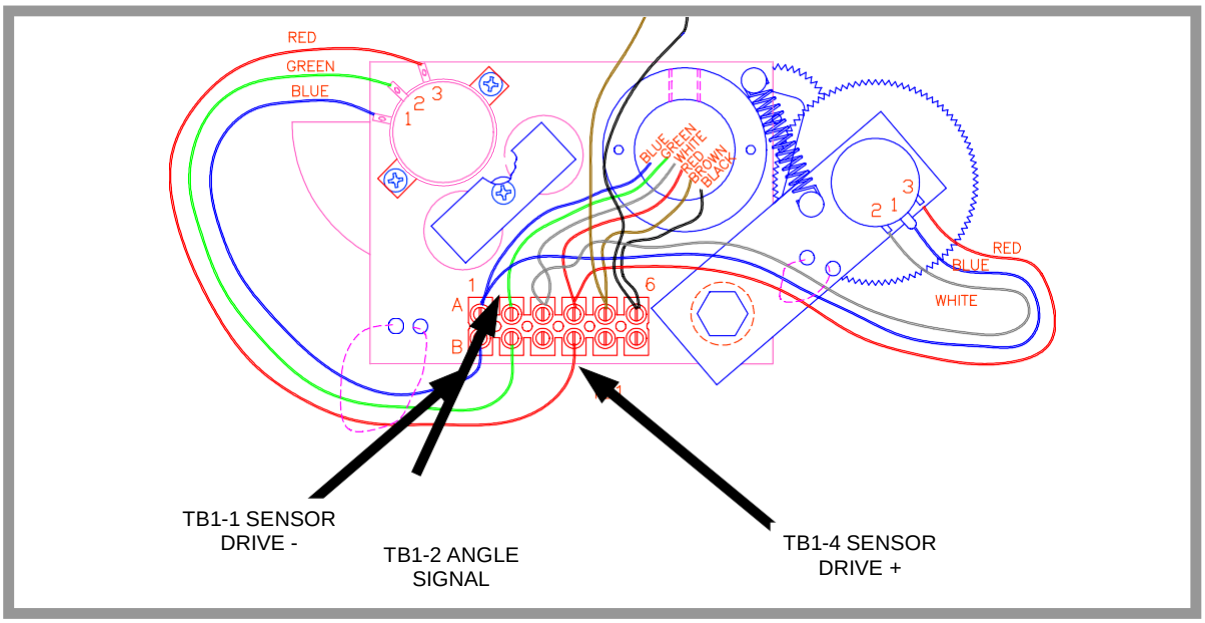


FIGURE 6.6 SENSOR BASEPLATE ASSEMBLY WIRING

ANGLE SENSOR SETUP

The following procedures define how to reset and calibrate the ANGLE SENSOR, as required.

PHYSICAL ZERO

It may be necessary to ensure that the angle sensor potentiometer is correctly set to its physical "zero" setting with the boom at 0° (ZERO). This ensures that the sensor will correctly measure the full angle range of the boom.

1. Using an inclinometer, set the boom to 0° (ZERO).
2. Loosen the two securing screws on either side of the sensor potentiometer just enough to allow the sensor potentiometer to be turned by hand. Do not remove the screws and do not put pressure on the terminals exiting the sensor.
3. Measuring the voltage between TB1-2 and TB1-1 (see Figure 6.7), carefully rotate the potentiometer until the voltage measures 0.4 volts. Rotating the sensor counterclockwise will increase the voltage. Rotating clockwise will reduce the voltage. Only fine adjustments are required. Do not touch the pendulum hanging behind the sensor assembly, as this will affect the reading.
4. Tighten the securing screws and check that the voltage remains at 0.4 volts.

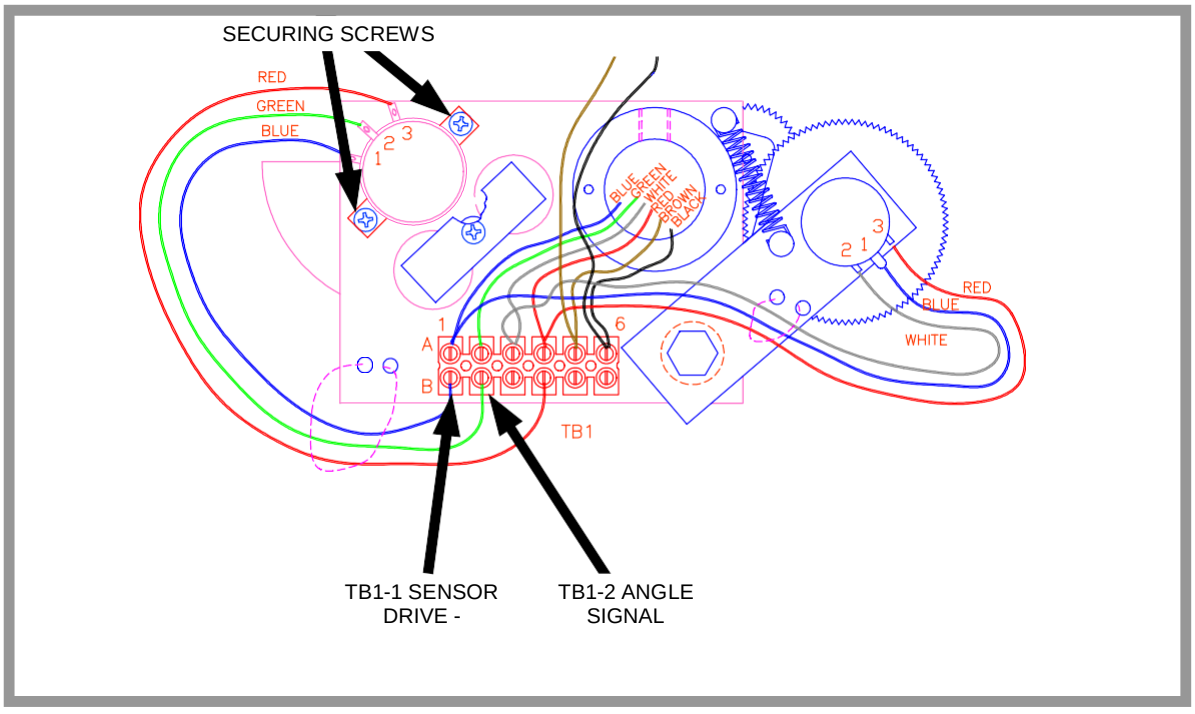


FIGURE 6.7 SENSOR BASEPLATE ASSEMBLY WIRING

ZERO CALIBRATION

The computer must be able to identify where the ZERO point of the angle sensor has been set. It is, therefore, necessary to calibrate the zero setting of the potentiometer.

Before continuing, make sure that the mechanical (physical) zero has been properly set, as described in SECTION 6.9.1.

1. Using an inclinometer, set the boom to 0° (zero).
2. Enter the CALIBRATION MODE at the display console. (SEE SECTION 10.2)
3. Select Command 02, SENSOR ZERO. (See SECTION 10.4.3)
4. Select sensor No. 3.
5. Zero the extension sensor.
6. Before exiting the command, check that the displayed value is between -4 and +4.

SPAN CALIBRATION

The computer must be able to treat measurements of the angle provided by the angle sensor. It is therefore necessary to calibrate the SPAN of the angle potentiometer.

Before continuing, ensure that the calibration zero has been properly set, as described in SECTION 6.9.2.

1. Boom up to a high angle (at least 70°) and measure the angle with an inclinometer.
2. Enter the CALIBRATION MODE at the display console. (See SECTION 10.2)
3. Select Command 03, SENSOR SPAN. (See SECTION 10.4.4.)
4. Select sensor No. 3.
5. Calibrate the angle span using the angle as measured in step 1.

NOTE

The required accuracy of measured angles is within 0.2°.

When taking boom angle measurements; always use a good quality inclinometer. Many inclinometers are only accurate at 0° (level). Ensure that a reliable position on the top of the boom is used to measure the angle and that the inclinometer will provide an accurate reading at 0° and at 70°.

6. Before exiting the command, check that the displayed value is between -0.1° and +0.1°.

EXTENSION REEL REPLACEABLE PARTS

The EXTENSION REEL is field-serviceable in every respect except for the spring chamber/extension reel surface and shaft assembly. Failure of the recoil spring, damage to the shaft or reel surface and side plates requires complete replacement of the extension reel.

The following parts of the extension reel, are field-replaceable:

- EXTENSION/REEL-OFF CABLE ASSY
- SLIP-RING ASSEMBLY
- SENSOR BASEPLATE ASSEMBLY
- CABLE TAIL ASSEMBLY (SIGNAL CABLE)
- COVER

EXTENSION REEL-OFF CABLE

The EXTENSION REEL-OFF CABLE, running from the extension reel to the main boom head, carries the Anti Two-Block signal from the switches at the main boom head, aux head and erected jib/fly. The cable is made from stainless steel wire and a durable outer sheath. Damage to the cable will often result in bad Two-Block signals or bad measurement of boom extension. If the cable has been broken or damaged in any way, it can be field-replaced.

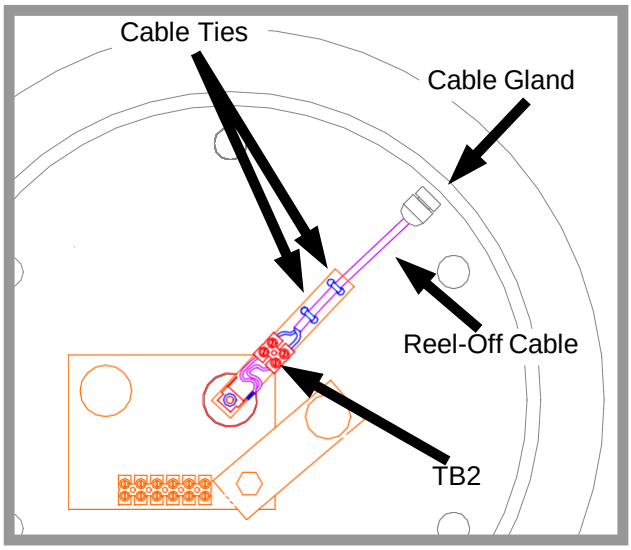


FIGURE 6.8 REEL-OFF CABLE CONNECTION ON THE EXTENSION REEL

- **REMOVING THE EXTENSION REEL-OFF CABLE**

1. Fully retract and lower the boom. Then, disconnect the REEL-OFF CABLE from the Anti Two-Block switch or connector.
2. Gripping the cable firmly, release it from the tie-off post.
3. Continue to grip the cable firmly while allowing it to fully wind back onto the extension reel.
4. Remove the extension reel cover.
5. Cut the 2 tie-wraps that secure the extension reel-off cable to the slip-ring support arm.
6. Unscrew the extension reel-off cable from the terminal block on the slip-ring support arm.
7. Loosen the gray cable gland mounted on the cheekplate.
8. Pull the existing extension reel-off cable out through the cable gland.

- **INSTALLING THE EXTENSION REEL-OFF CABLE**

1. Loosen the strain relief on the cheekplate and feed the EXTENSION REEL-OFF CABLE through the wall of the cheekplate. Leave enough slack to work easily with the cable.
2. If not already stripped, remove 1" of the outer jacket of the cable with an X-ACTO knife.
3. Unravel the stainless steel braid and twist it into a single wire.
4. Remove 1/4" insulation from the center wire. The insulation bonded to the center wire is difficult to remove. Remove small increments about 0.1" at a time with wire strippers.
5. Connect the extension reel-off cable to TB2 on the arm of the slip-ring. The braided wire connects to the black wire and the center core connects to the brown wire. Using two cable ties, tie the cable to the arm of the slip-ring.
6. Secure the extension reel-off cable to the arm of the slip-ring with 2 tie-wraps.
7. Adjust the cable to bend slightly from the strain relief to the slip-ring. Rotate the extension reel. Ensure that the path of the new cable is unimpeded; then, tighten the strain relief.
8. Wind the extension reel-off cable onto the extension reel in a single layer.
9. Set pre-tension (5 turns counterclockwise). Thread the extension reel off-cable through the cable guides. Attach the cable to the boom tie-off-post and connect it to the Anti Two-Block switch.
10. Follow the EXTENSION SENSOR SETUP PROCEDURE to set the potentiometer zero. Recalibration of the extension span should not be necessary.
11. Fully telescope the boom in and out at least twice, ensuring that the reel-off cable remains in a single flat layer on the drum surface and the length display on the display console is accurate with a fully extended or fully retracted boom. Any stacking of the cable on the extension reel

surface will cause measurement errors. If this is the case, it may be necessary to check that the first cable guide aligns correctly with the outside edge of the extension reel surface.

12. Reinstall the cover of the extension reel, ensuring that the "O" ring on the inside of the Extension Reel is intact.

SLIP-RING ASSEMBLY

The main purpose of the SLIP-RING ASSEMBLY is to provide an electrical path for the feed and switch signal return, between the Two-Block switch and the system computer.

It is unlikely that the slip-ring assembly should ever require repair or replacement. If such an event arises, however, both the upper and lower halves of the slip-ring assembly must be replaced at the same time.

Failure of the slip-ring assembly will most likely result in a continuous Two-Block alarm.
For information on testing and checking the slip-ring assembly, refer to the Anti-Two-Block function in SECTION 7.

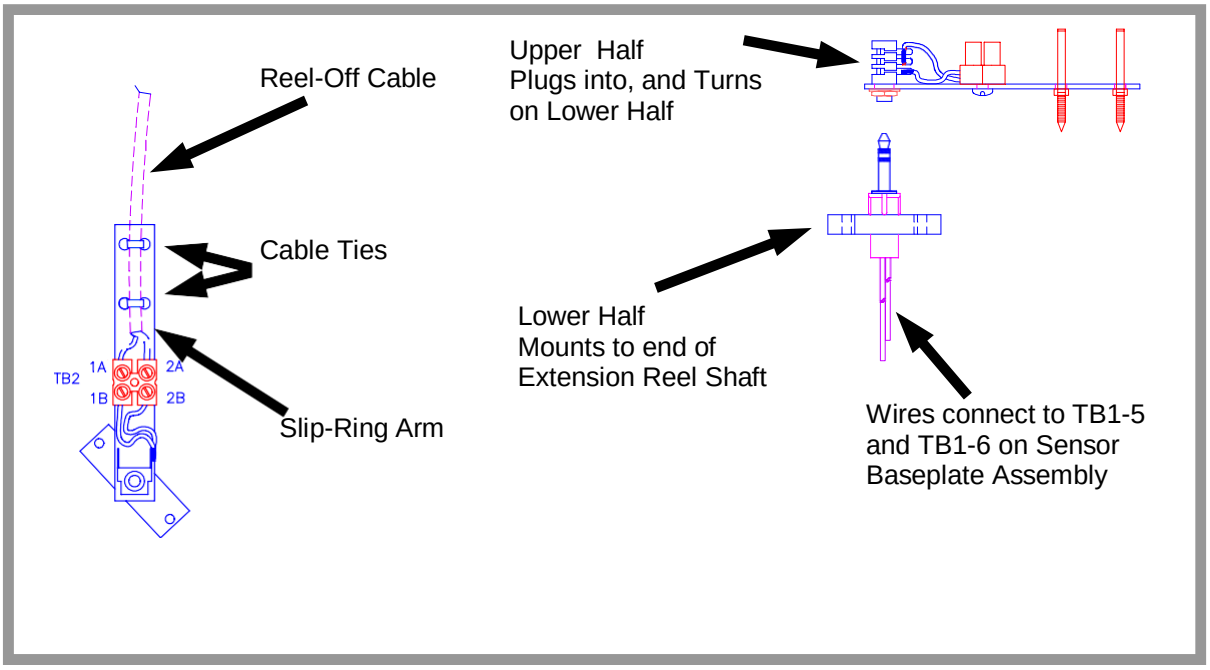


FIGURE 6.9 SLIP-RING ASSEMBLY

- **REMOVING THE SLIP-RING ASSEMBLY**

1. Remove the extension reel cover.
2. Holding the reel-off cable on the arm of the slip-ring, cut the tie wraps.
3. Unscrew the reel-off cable from TB2 on the arm of the slip-ring.
4. Unscrew both Phillips screws that hold the lower half of the slip-ring on the shaft; remove the slip-ring.
5. Disconnect the two wires connecting the lower half of the slip-ring assembly at TB1-5 and TB1-6 on the sensor baseplate assembly.

- **INSTALLING THE SLIP-RING ASSEMBLY**

The new SLIP-RING ASSEMBLY is pre-lubricated with grease. Do not wipe off lubrication.

1. Attach the brown slip-ring wire from the lower half of the new slip-ring to TB1-5 on the sensor baseplate assembly. Make sure that the brown signal wire is also correctly connected.
2. Attach the black (or white) slip-ring wire from the lower half of the new slip-ring to TB1-6 on the sensor baseplate assembly. Make sure that the black signal cable wire is also correctly connected.
3. Screw the bottom half of the slip-ring to the shaft with the two Phillips screws, making sure that wires exiting through the center of the shaft are not trapped.
4. Connect the extension reel-off cable to TB2 on the arm of the slip-ring. The braided shield connects to the slip-ring TB2 black wire and the center of the cable connects to the slip-ring TB2 brown wire.
5. Secure the extension reel-off cable to the arm of the slip-ring with two cable ties.
6. Ensure that the slip-ring is plugged in all the way.
7. Replace the extension reel cover.

SENSOR BASEPLATE ASSEMBLY

The SENSOR BASEPLATE ASSEMBLY supports both the extension and angle sensors and provides interconnection between the sensors, the Two-Block switch signal to the slip-ring, and the signal cable to the system computer.

Electrical or mechanical failure of either the angle sensor or the extension sensor potentiometers may not be field-repaired, since the angle sensor pendulum is factory set on the potentiometer shaft, and the extension potentiometer gear contains a protection clutch which is difficult to replace in the field. In the event of failure of either of these items, the whole sensor baseplate assembly must be replaced.

The terminal block (TB1), mounted on the assembly, provides wiring connection for all internal parts of the extension reel, and the signal cable connecting the reel to the system computer. Most electrical diagnoses of the boom sensors may be made at this terminal block.

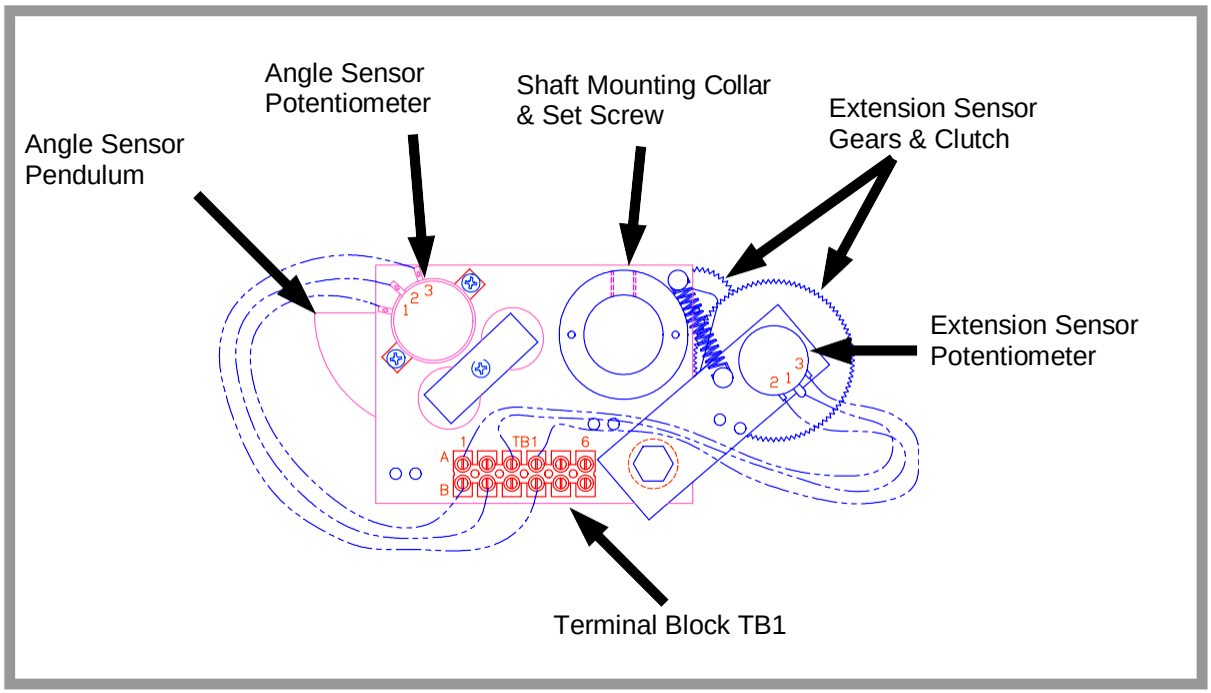


FIGURE 6.10 SENSOR BASEPLATE ASSEMBLY

- **REMOVING THE SENSOR ASSEMBLY**

1. Remove the aluminum cover on the extension reel.
2. Unscrew the screws holding the slip-ring to the mounting ring of the SENSOR ASSEMBLY.
3. Disconnect the brown and black wires.
4. Disconnect the signal cable wires to terminal block TB1.
5. Using a 5/32" Allen wrench, loosen the set-screw that holds the baseplate on the shaft.
6. Remove the sensor assembly.

- **INSTALLING THE SENSOR ASSEMBLY**

Place the boom in a horizontal position when installing the SENSOR ASSEMBLY.

1. Feed the wires coming out of the main shaft through the mounting collar on the sensor assembly.
2. While pulling both extension sensor gears out, against the spring, slide the sensor assembly onto the shaft until the top of the shaft aligns with the top of the mounting collar. Align the top edge of the assembly parallel with the boom.
3. Tighten the set-screw and release the gears allowing them to mesh with the extension reel spline. Route the wires to the terminal block and hook up the wires, as indicated below. Refer to Figure 6.10.
4. Tuck the unconnected remaining yellow and orange wires down into the shaft.

SENSOR ASSEMBLY TERMINAL BLOCK WIRING

TERMINAL	TB1-1	TB1-2	TB1-3	TB1-4	TB1-5	TB1-6
WIRE COLOR	BLUE	GREEN	WHITE	RED	BROWN	BLACK
SIGNAL	SENSOR DRIVE -	ANGLE	EXTENSION	SENSOR DRIVE +	ATB-SIGNAL	ATB-FEED

5. Screw the slip-ring assembly to the baseplate of the sensor assembly.
6. Connect the brown wire on the slip-ring assembly to TB1-5; connect the black wire to TB1-6. Strip wires, if not already stripped.
7. **Note:** Ensure that the wires lay flat. Ensure that there will be enough space to allow the slip-ring arm to freely rotate.
8. Check the wiring and then follow the procedures to set up both the angle and extension sensors later in this section.

SIGNAL CABLE ASSEMBLY

The SIGNAL CABLE ASSEMBLY provides interconnection between the extension reel sensors, the Two-Block switch and the system computer.

- **REMOVING THE EXTENSION REEL FROM THE BOOM**

1. Fully lower and retract the boom.
2. Disconnect the EXTENSION REEL CABLE from the Anti Two-Block switch.
3. Gripping the extension reel cable firmly, remove it from the tie-off post.
4. Maintain a firm hold on the extension reel cable as the cable unwinds back onto the reel.
5. Secure the end of the extension reel cable to prevent unwinding.
6. Disconnect the signal cable at the distal end.
7. Unbolt the extension reel from the crane with a wrench.

- **REMOVING THE SIGNAL CABLE FROM THE EXTENSION REEL**

1. Remove the cover from the extension reel.
2. Remove the slip-ring on the baseplate of the sensor assembly.
3. Disconnect all wires from the sensor assembly **EXCEPT** for the 6 wires leading to the angle and extension sensor potentiometers.
4. To protect the sensors within the extension reel, use two screws to temporarily reattach the cover of the extension reel.
5. Turn over the extension reel with cover attached, exposing the back of the device.
6. With the wires still disconnected, pull the SIGNAL CABLE out of the main shaft in the center of the reel. This cable has a strain-relief encircled with an "O"-Ring, creating a tight fit that seals out water.

   NOTE: If it is difficult to remove the cable, use the Insertion/Extraction tool from the **FRONT** of the extension reel to release the cable.

- **INSTALLING THE SIGNAL CABLE**

1. Unpack the new SIGNAL CABLE and ensure that the "O"-ring on the strain-relief is greased.
2. With the back of the extension reel still exposed, insert the end of the signal cable with the "O"-ring into the mounting plate and down the shaft in the center of the reel.
3. Seat the strain-relief, with attached "O"-ring, as follows, using the tool provided in the kit.
4. Bend the cable to the side. Position the hollowed-out section of the tool on the strain-relief plug at the top of the shaft.
5. With a hammer, gently tap the top of the tool forcing the strain-relief into proper position in the shaft. Continue to tap gently until the strain-relief plug will go no further.
6. Turn over the extension reel and remove the cover.
7. Connect the wires to the terminal block on the baseplate, as indicated below.

SIGNAL CABLE TERMINAL BLOCK WIRING

TERMINAL	TB1-1	TB1-2	TB1-3	TB1-4	TB1-5	TB1-6
WIRE COLOR	BLUE	GREEN	WHITE	RED	BROWN	BLACK
SIGNAL	SENSOR DRIVE -	ANGLE	EXTENSION	SENSOR DRIVE +	ATB-SIGNAL	ATB-FEED

8. Tuck the unconnected remaining yellow and orange wires down into the shaft.
9. Connect the brown wire from the slip-ring assembly to TB1-5; connect the black wire to TB1-6. Strip wires, if not already stripped.
10. Screw the slip-ring assembly to the baseplate of the sensor assembly.
11. **NOTE:** Ensure that the wires lay flat and toward the terminal connectors, as shown in Figure 6.1. Ensure that there will be enough space to clear the wires when the arm of the slip-ring rotates.
12. Replace the cover on the extension reel; reinstall the extension reel.

SECTION 7 ANTI TWO-BLOCK FUNCTION

ANTI TWO-BLOCK FUNCTION OVERVIEW

This section describes fault diagnoses of the Anti Two-Block detection circuit. For details of function kickouts (including the Anti Two-Block kickout), refer to SECTION 8.

The computer supplies a protected positive feed to the Anti Two-Block switches at the boom/jib head via the extension reel signal cable, slip-ring, and extension reel-off cable. With the Anti Two-Block weight hanging freely on the switch(es), the switch contact is closed and the signal return to the computer is high (6.25 volts). When the weight is lifted by the hook block, the switch contact is opened, and the computer will sense a low signal input (0 volts) from the A2B signal return.

Since the computer checks the protected feed voltage internally, the system is capable of detecting a short circuit of the feed (or the A2B signal return when the switch is closed) to the crane chassis. fault codes are defined in SECTION 2.

The Anti Two-Block detection circuit is probably the most susceptible part of the System, since it is carried through so many of the system components. Often, most problems with this circuit may be identified through inspection of cables, switches, and the extension reel. Damage to these parts may result in continuous or intermittent A2B alarms.

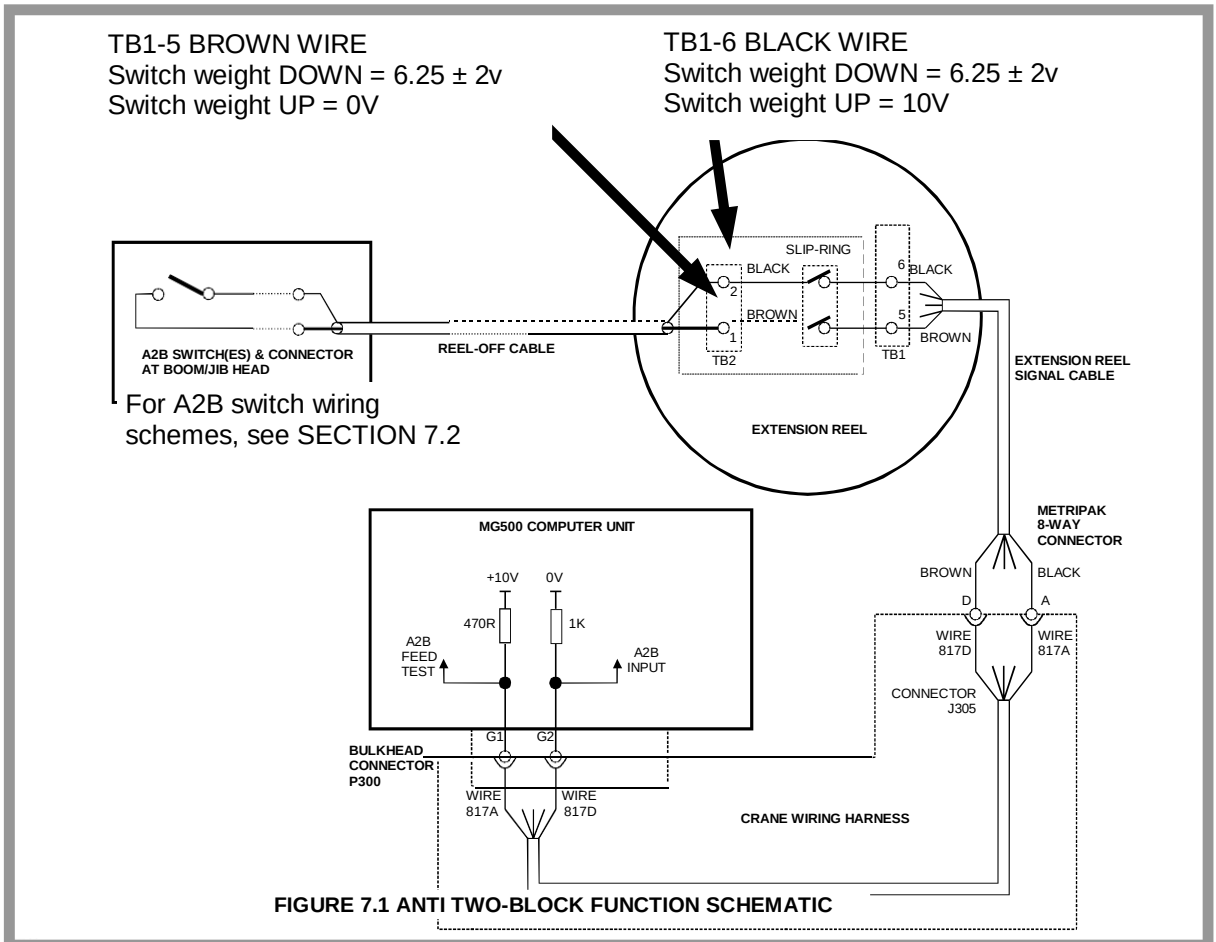


FIGURE 7.1 ANTI TWO-BLOCK FUNCTION SCHEMATIC

ANTI TWO-BLOCK SWITCH CONFIGURATIONS

This section details wiring schemes for Anti Two-Block switches.

MS CIRCULAR CONNECTORS WITH MAIN/BOTH/JIB SWITCH

Cranes fitted with Anti Two-Block switches using circular connectors, will also have a main boom head switch which contains a selector switch for MAIN/BOTH/JIB switch detection selection.

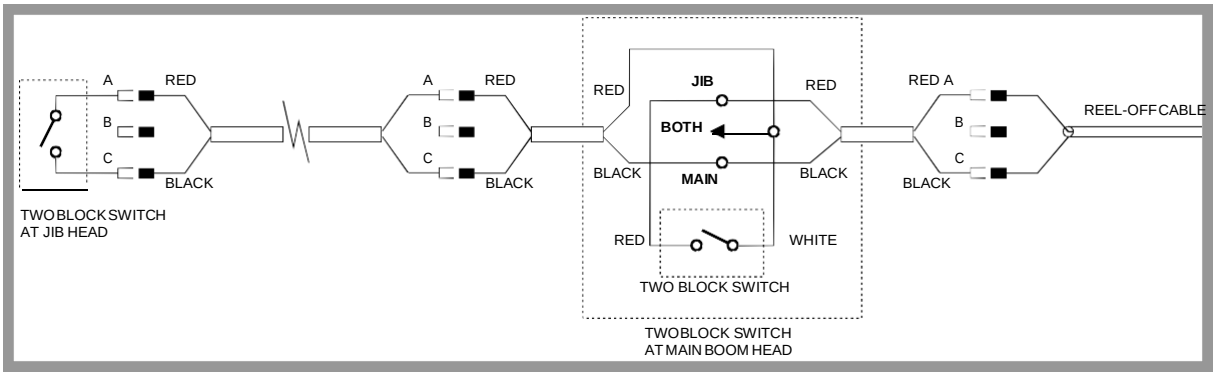


FIGURE 7.2 MS CIRCULAR CONNECTOR SCHEMATIC

RECTANGULAR PLUG-IN CONNECTORS

Cranes fitted with rectangular style plug-in connectors do not have a MAIN/BOTH/JIB selector switch in the main boom head A2B switch.

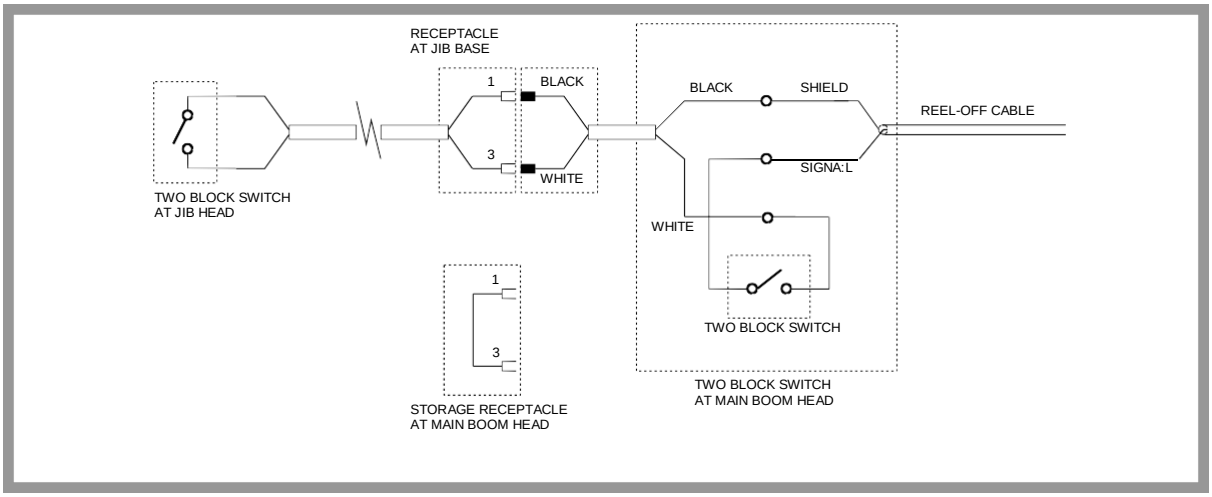


FIGURE 7.3 RECTANGULAR PLUG-IN CONNECTOR SCHEMATIC

CHECKING THE EXTENSION REEL-OFF CABLE

The outer braid of the cable carries the Anti Two-Block feed to the switches. If the cable sheath is damaged, this may cause a short circuit to the boom/chassis. If this is the case, a fault code above “B 8” will be indicated (See SECTION 2.3.2). The same fault code will be indicated if the A2B switch is closed and the inner core of the cable is shorted to chassis at some point in the wiring.

- Carefully inspect the reel-off cable for wear.
- Check for signs of damage to the outer sheath of the cable.
- Check for any signs of severe “kinking” or crushing of the cable.

CHECKING THE ANTI TWO-BLOCK CIRCUIT

Before continuing, ensure that connectors are correctly connected to the A2B switches at the boom head/jib.

1. Remove the extension reel cover.
2. Disconnect the slip-ring arm from the plug by pulling it away from the center of the reel.
3. Close the A2B switch at the boom head by suspending the weight from it or pulling on the chain.
4. Measure the resistance between TB2-1 & TB2-2 terminal connections on the sensor arm.
5. With the A2B switch closed, the resistance should be less than 300 ohms. If not, this suggests that the reel-off cable, A2B switch, or one of the boom head connectors has an Open circuit.

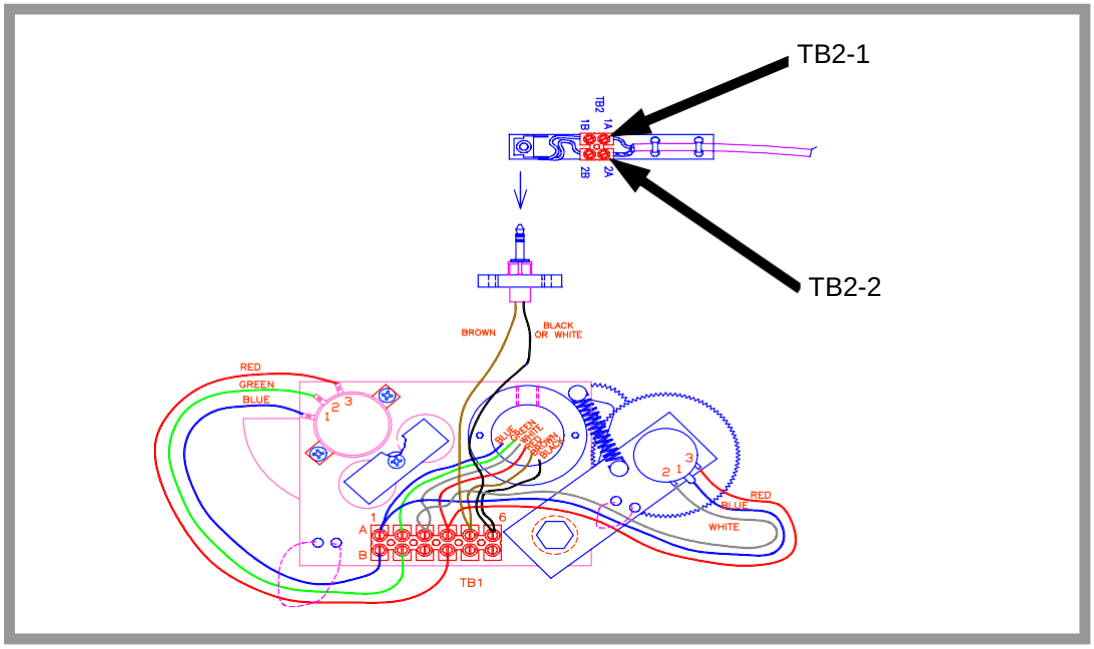


FIGURE 7.4 SENSOR ASSEMBLY WIRING AND SLIP-RING

6. Open the A2B switch at the boom head by lifting the weight.
7. Measure the resistance between TB2-1 & TB2-2 terminal connections on the sensor arm.
8. With the A2B switch open, the resistance should be greater than 10,000 ohms. If not, this suggests that the reel-off cable, A2B switch, or one of the boom head connectors has a short circuit.

SECTION 8 POWER, KICKOUT & BOOM MODE OUTPUTS

This section provides schematic outlines of outputs from the computer and is provided for information only. Since most of these functions are contained within the computer design and crane wiring harness, only limited fault diagnosis may be carried out. The FKO fuse (FS2) is described in SECTION 3.

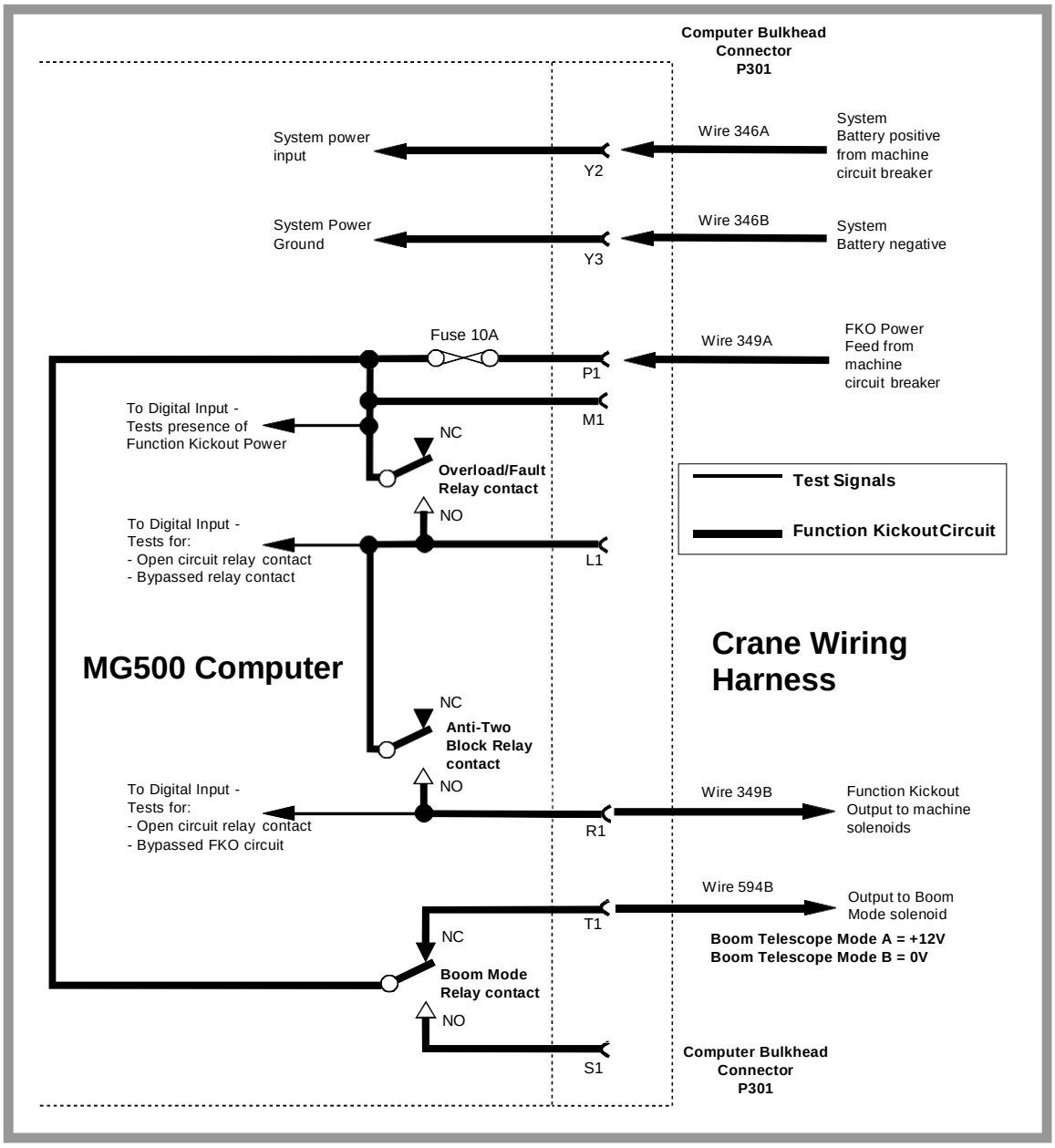


FIGURE 8.1 POWER, FUNCTION KICKOUT & BOOM MODE SCHEMATIC

SECTION 9 SWING SENSOR

SWING SENSOR OVERVIEW

The SWING SENSOR measures the angle of the upper structure of the crane relative to its carrier. This angle is then used to select capacity charts and operator swing alarms/working area alarms.

In the event that the swing sensor fails, the computer will be unable to select a valid capacity chart.

For fault diagnosis, the swing sensor may be accessed by removing the cover of the collector at the cranes swing center. See Figure 9.1 below.

For swing sensor replacement procedures, consult factory service.

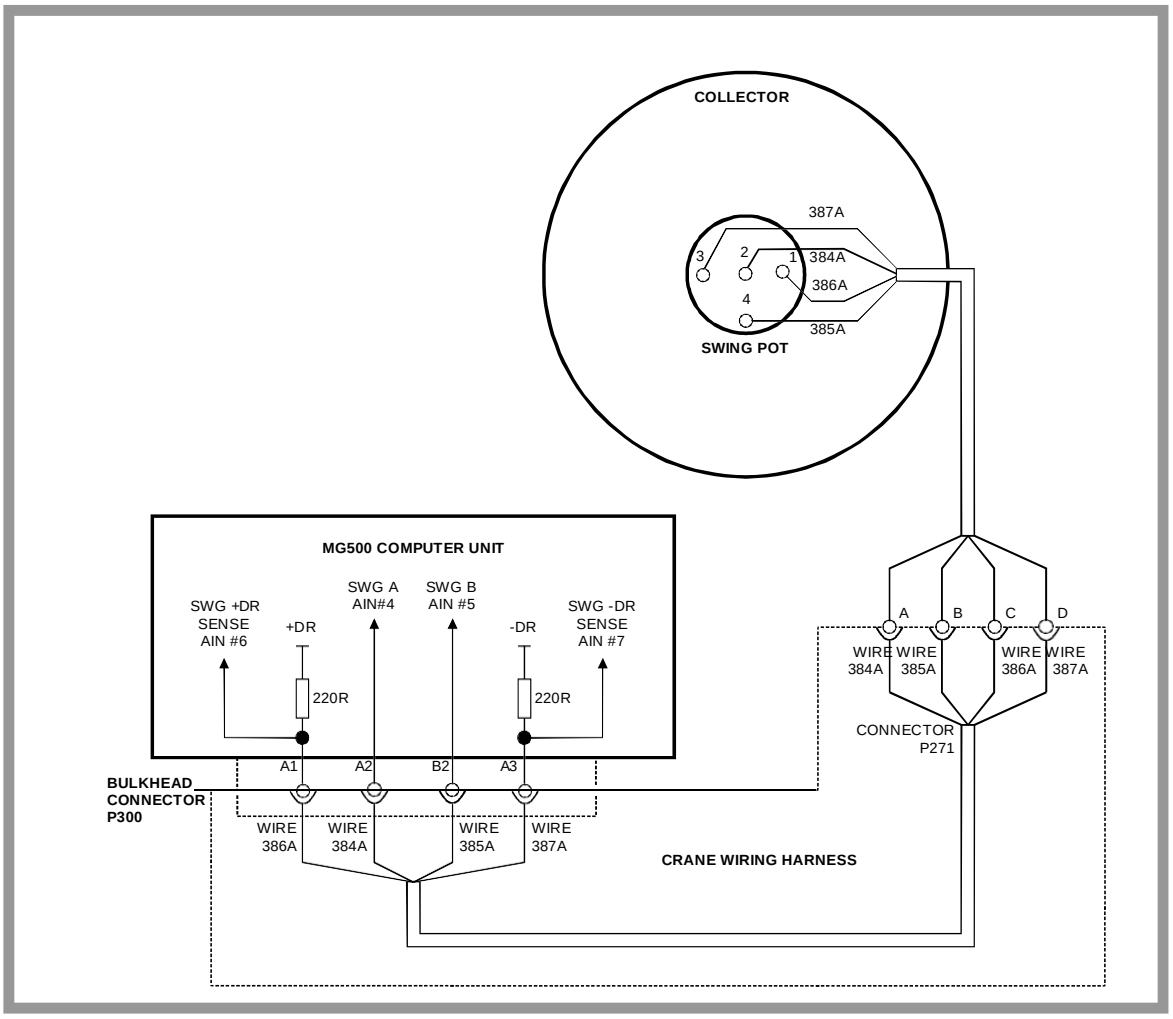


FIGURE 9.1 SWING SENSOR SCHEMATIC

CHECKING THE SWING SENSOR DRIVE VOLTAGE

1. Remove the collector ring cover to expose the swing sensor.
2. With the system power turned on, measure the voltage between terminal 1 of the swing sensor and crane ground. The voltage should be between 4.4 and 4.8 volts.
3. Measure the voltage between Terminal 3 of the swing sensor and crane ground. Thevoltage should be between 0.2 and 0.5 volts.

Voltages outside of those shown in steps 2 and 3 indicate a problem with the swing sensor or cabling connections. If voltages are incorrect, proceed to SECTION 9.4. If voltages are correct, proceed to SECTION 9.3.

CHECKING THE SWING SENSOR OUTPUT VOLTAGE

1. Remove the collector ring cover to expose the swing sensor.
2. With the system power turned on, measure the voltage between Terminal 2 of the swing sensor and crane ground. The voltage should be between 0.2 and 4.8 volts.
3. Measure the voltage between Terminal 4 of the swing sensor and crane ground. Thevoltage should be between 0.2 and 4.8 volts.

Voltages outside of those shown in Steps 2 and 3 indicate a problem with the swing sensor or cabling connections. If voltages are incorrect, proceed to SECTION 9.4.

CHECKING THE SWING SENSOR RESISTANCE

1. Disconnect the connector P271 (behind the collector ring).
2. Measure the resistance between pins C and D of the connector on the swing sensor side. The resistance should be between 2200 and 2800 ohms.
3. Measure the resistance between pins A and B of the connector on the swing sensor side. The resistance should be between 1800 and 2300 ohms.

NOTE: Resistances outside of those shown in Steps 2 and 3 indicate a problem with the swing sensor or associated cable connections. If resistances are incorrect, replace the swing sensor and its cable.

SWING SENSOR SETUP AND CHECKS

The following procedures may be used to check or setup the SWING SENSOR. Only two setup operations are required (ZERO and DIRECTION). Unlike other system sensors, the swing sensor requires no span calibration to operate. Span is automatically calculated by the computer.

CHECKING AND SETTING ZERO

The 0° (zero) angle of the upper structure should be set with the house-lock engaged over front for all types of cranes. Before continuing, ensure that the upper structure is positioned over FRONT and the the house-lock is engaged.

1. Enter the CALIBRATION MODE at the display console.(See SECTION 10.2.)
2. Select Command 04, SWING SENSOR - ZERO. (See SECTION 10.4.6.)
3. Check that the angle value displayed is between -0.5° and + 0.5°. If not, reset the zero by pressing the zero key.

CHECKING AND SETTING DIRECTION

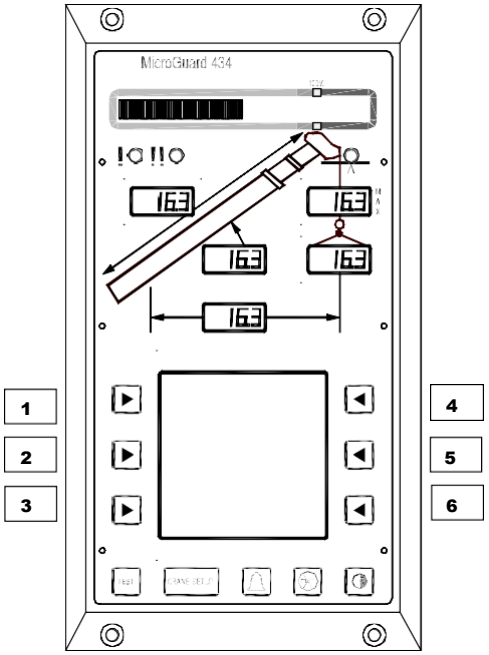
1. Enter the CALIBRATION MODE at the display console. (See SECTION 10.2.)
2. Select Command 04, SWING SENSOR - DIRECTION. (See SECTION 10.4.7.)
3. Remove the house-lock and swing to the right. Check that the angle value displayed increases from zero. If not, the displayed value will immediately jump to over 350° and continue counting down as the crane upper is swung to the right. If this is the case, press the direction key to reverse the calibrated direction of the sensor.

SECTION 10 APPENDIX

SECTION 10.1 THE DISPLAY UNIT

The display unit, shown below, provides the interface between the user and the Calibration Mode functions. Six arrow keys surrounding the display screen are used to enter and exit COMMANDS and to respond to on-screen prompts during the function routines.

The arrow keys graphically identified here with numerals are used to operate the MicroGuard® 434/500 System Calibration Mode functions. COMMIT THE NUMERALS AND ASSOCIATED POSITIONS TO MEMORY. THEY WILL BE REFERENCED THROUGHOUT THE CALIBRATION COMMANDS. THE 'TEST' KEY AND THE 'CRANE SETUP' KEY POSITIONED AT THE BASE OF THE DISPLAY UNIT ARE ALSO USED IN THE CALIBRATION MODE.



SECTION 10.2 THE CALIBRATION MODE

Use of the calibration commands described in this manual require that the MicroGuard® 434/500 System be in the Calibration Mode of operation.

TO ENTER THE CALIBRATION MODE

SIMULTANEOUSLY PRESS AND HOLD THE TEST AND CRANE SETUP BUTTONS UNTIL PROMPTED BY THE DISPLAY TO ENTER THE CALIBRATION CODE.

TO ENTER THE CALIBRATION CODE

PRESS THE DISPLAY ARROW KEYS IDENTIFIED AS: 1 6 3 4 IN THE SEQUENCE SHOWN (REFER TO PAGE 68.)

NOTE: IF THE WRONG SEQUENCE IS USED OR IF THE ENTRY IS NOT COMPLETED WITHIN 5 SECONDS, THE CALIBRATION ENTRY WILL BE ABORTED AND MUST BE REENTERED.

NOTE: IF A PICTURE OF THE WORKING SCREEN APPEARS, ENTER THE CALIBRATION MODE AND THE CALIBRATION CODE AGAIN.

WHEN IN THE CALIBRATION MODE

THE TWO-BLOCK ALARM AND KICKOUT ARE OPERATIONAL. ALL OTHER ALARM KICKOUTS AND AUDIO ALARMS WILL REMAIN INACTIVE UNTIL THE SYSTEM IS OUT OF THE CALIBRATION MODE.

ALL VISUAL WARNING ALARMS WILL REMAIN ACTIVE.

SECTION 10.3 NUMBER ENTRY

The MicroGuard® 434/500 series displays do not have number entry keys. Use the following number entry procedure to enter a number into the system. The display will change as the numerical data is processed. The symbols used to enter numbers are shown below.

•	SELECTS A DECIMAL POINT
0 - 9	SELECTS A DIGIT FROM 0-9. USE THE CORRESPONDING ROW KEYS TO CHANGE A NUMERAL
-	MINUS SIGN
C	CLEARS A CURRENTLY DISPLAYED NUMERAL
<	DELETES THE LAST ENTRY

After starting the number entry routine, the display will flash the currently selected numeral surrounded by brackets < >. When entering negative numbers, select the minus sign first. Brackets will always surround the selected entry.

Press the arrow key nearest the first numeral to be entered until brackets surround the numeral. Press the top left arrow key to enter the numeral or symbol into the system. Any number from -999.9 to 999.9 can be selected and entered this way. Press the arrow key nearest the word 'EXIT' after all numerals/ symbols are entered.

<0> 1 2 3 4 5 6

If a number requires a decimal point, press the arrow key nearest the decimal point to move the bracket < > around the decimal point. Press the top left arrow key to enter the decimal point into the system.

7 8 9 < **<•>** - C

Press the arrow key nearest the minus sign and select the minus sign.

Press the top left arrow key to enter the minus sign.

7 8 9 < • **<->** C

If an error is made in data entry, press the arrow key nearest **C (clear)** and select **C**. Press the top left arrow key, which will delete the complete entry. Move the cursor back to the entry of digits and reenter the correct number.

7 8 9 < • - **<C>**

To delete the last entry, press the arrow key nearest < and select it. Next, press the top left arrow key to complete the action.

7 8 9 **< < >** • - C

SECTION 10.3 NUMBER ENTRY continued

THE FOLLOWING STEPS ILLUSTRATE THE NUMBER ENTRY PROCEDURE

WHEN COMPLETED, THE NUMBER SHOULD READ

-123.45

PRESS THE ARROW KEY NEAREST THE REQUIRED SELECTION UNTIL BRACKETS SURROUNDTHE SELECTION.
PRESS TOP LEFT ARROW KEY TO ENTER THE DATA.

1. SELECT THE MINUS SIGN < - >
2. ENTER THE MINUS SIGN
3. SELECT THE FIRST DIGIT < 1 >
4. ENTER THE FIRST DIGIT
5. SELECT THE SECOND DIGIT < 2 >
6. ENTER THE SECOND DIGIT
7. SELECT THE THIRD DIGIT < 3 >
8. ENTER THE THIRD DIGIT
9. SELECT THE DECIMAL POINT < • >
10. ENTER THE DECIMAL POINT
11. CHOOSE THE FIRST DECIMAL PLACE < 4 >
12. ENTER THE FIRST DECIMAL PLACE
13. CONFIRM < 4 > AND COMPLETE < 1 > THE CALIBRATION.

SECTION 10.4 CALIBRATION COMMANDS

10.4.1 COMMAND 01

WARNING PERFORMING A CRANE DATA RESET WILL REPLACE CALIBRATED DATA WITH DATA STORED IN THE SYSTEM CHIP.

NOTE 1: IF THIS IS NOT A PROTOTYPE CALIBRATION, ALL CALIBRATION DATA WILL BE STORED IN THE SYSTEM CHIP. IN ORDER TO MODIFY THIS DATA, DOWNLOAD NEW OR CHANGED DATA. THE 'CRANE DATA RESET' WILL NEED TO BE PERFORMED.

NOTE 2: ALWAYS PERFORM CRANE DATA RESET ON A NEW OR PROTOTYPE SYSTEM BEFORE BEGINNING CALIBRATION OR TESTING.

COMMAND 01 - CRANE DATA

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND
and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.

1. CHOOSE MENU UP OR MENU DOWN AND GO TO 01 CRANE DATA ..... 2 OR 3

2. START 01 CRANE DATA 1

3. RESET CRANE DATA 1

4. CHOOSE YES! CALIBRATE OR NO! ABORT ..... 1 YES/ 3 ABORT

5. ENTER THE CALIBRATION CODE. 1 6 3 4

**6. THE DISPLAY WILL READ: CRANE DATA 'CALIBRATING.'
WHEN THE DISPLAY CHANGES TO 'PERSONALITY GOOD,' EXIT THE ROUTINE..... 6**

7. IF THE DISPLAY READS: 'PERSONALITY NOT GOOD," RETURN TO STEP 3, 'RESET CRANE DATA' AND CONTINUE. 1

SECTION 10.4.2 COMMAND 02 - ZERO EXTENSION

COMMAND 02 - ZERO BOOM EXTENSION SENSOR

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.

1. CHOOSE MENU UP OR MENU DOWN AND GO TO 02 ZERO SENSOR ..... 2 OR 3

2. START 02 ZERO SENSOR 1
THE DISPLAY WILL READ: ZERO NO. 2 XXX (ACTUAL INPUT).

3. CONFIRM THE SELECTION OF SENSOR NO. 2..... 1
THE DISPLAY WILL READ: ZERO SENSOR YES! CALIBRATE!
OR NO, ABORT.

4. START THE CALIBRATION OF ZERO SENSOR NO. 2..... 1
THE DISPLAY WILL READ: ZERO NO. 2 XXX (ZEROED INPUT),
OR NO, EXIT/ABORT (THE CALIBRATION)..... 3

5. EXIT THE ROUTINE OR SEE STEP 6 6

6. CHOOSE MENU UP OR MENU DOWN TO CHANGE SENSOR. ..... 2 OR 3

SECTION 10.4.3 COMMAND 02 ZERO ANGLE

COMMAND 02 - ZERO BOOM ANGLE SENSOR

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.

1. CHOOSE MENU UP OR MENU DOWN AND GO TO 02 ZERO SENSOR.....2 OR 3

2. START 02 ZERO SENSOR.....1
THE DISPLAY WILL READ: ZERO NO. 2 XXX (ACTUAL INPUT).

3. CHOOSE MENU UP OR MENU DOWN AND GO TO ZERO NO. 3 ..... 2 OR 3

4. CONFIRM THE SELECTION.....1
THE DISPLAY WILL READ: YES! CALIBRATE! OR NO, EXIT/ABORT!

5. START THE CALIBRATION OF SENSOR NO. 3.....1
THE DISPLAY WILL READ ZERO NO. 3 XXX (ZEROED INPUT)
OR ABORT THE CALIBRATION.....3

6. EXIT THE ROUTINE 6
OR SEE STEP 7.

7. CHOOSE MENU UP OR MENU DOWN TO CHANGE SENSOR. .....2 OR 3

SECTION 10.4.4 COMMAND 03 SPAN - ANGLE

NOTE: THE INCLINOMETER OR MEASURING DEVICE USED TO CALIBRATE THE ANGLE OF THE MAIN BOOM MUST HAVE AN ACCURACY OF +/- 1°. USE OF A LESS ACCURATE DEVICE MAY RESULT IN CALIBRATION ERRORS.

NOTE: USE GREAT CARE IN THE CALIBRATION OF THE BOOM ANGLE SENSOR. ALL SUBSEQUENT CALCULATIONS ARE DEPENDENT ON THE ACCURACY OF THE CALIBRATION OF THIS SENSOR.

a) Raise the retracted boom to an angle between 60° and 65°; using an inclinometer, measure the angle.

b) **EXAMPLE:** 61.5°

c) Calibrate the span of the boom angle sensor as follows:

COMMAND 03 SPAN - BOOM ANGLE SENSOR

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.

1. CHOOSE MENU UP OR MENU DOWN AND GO TO 03 SPAN SENSOR.....2 OR 3

2. START 03 SPAN. 1

3. CHOOSE MENU UP OR MENU DOWN AND GO TO SPAN NO.3 (IF NOT ALREADY THERE).....2 OR 3
THE DISPLAY WILL READ:
SPAN No. 3 X.XX (or actual input when recalibrating).

4. START THE CALIBRATION OF SPAN NO. 3 1

5. USE THE NUMBER ENTRY PROCEDURE (PAGE 6) TO ENTER THE MEASURED BOOM ANGLE.

6. START THE CALIBRATION.....1 YES/3 ABORT
THE DISPLAY WILL READ: SPAN NO. 3 X.XX (boom angle entered)

7. EXIT THE ROUTINE.....6
OR GO TO STEP 8.

8. CHOOSE MENU UP OR MENU DOWN TO CHANGE SENSOR.....2 OR 3

SECTION 10.4.5 COMMAND 03 SPAN - EXTENSION

THROUGHOUT THIS PROCEDURE: DO NOT FULLY EXTEND THE BOOM IF THIS ACTION COULD CAUSE A TIPPING CONDITION.

CARRY OUT CALIBRATION PROCEDURES ONLY WITHIN THE STABILITY LIMITS OF THE CRANE.

a) With the boom fully retracted in a horizontal position, measure the distance from the boom pivot to the hook centerline. Note the distance.

b) Extend the boom as far as possible without tipping the crane.

c) Measure the distance from the boom pivot to the hook centerline. Note the distance.

d) Calculate boom extension from this formula: **Extended** length minus **Retracted** length equals **Extension** value.

EXAMPLE: IF THE EXTENDED BOOM LENGTH IS 72 FT AND THE RETRACTED BOOM LENGTH IS 30.5 FT, THE EXTENSION VALUE IS 72 – 30.5 = 41.5 FT

e) With the boom still fully extended, calibrate the **SPAN** of the **EXTENSION** (See steps below.)

COMMAND 03 SPAN - BOOM EXTENSION SENSOR

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. **ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.**

1. **CHOOSE MENU UP OR MENU DOWN AND GO TO 03 SPAN SENSOR ..... 2 OR 3**

2. **START 03 SPAN SENSOR 1**

3. **CHOOSE MENU UP OR MENU DOWN AND GO TO SENSOR NO. 2 ..... 2 OR 3**
THE DISPLAY WILL READ: SPAN NO. 2 X.XX (or actual input when recalibrating).

4. **START THE CALIBRATION OF SENSOR NO. 2 ..... 1**

5. **USE THE NUMBER ENTRY PROCEDURE (PAGE 6) TO ENTER EXTENSION VALUE.**

6. **CONFIRM OR ABORT THE CALIBRATION ..... 1 CONFIRM/ 3 ABORT**
THE DISPLAY WILL READ: SPAN NO. 2 XX.XX (extension value you entered).

7. **EXIT THE ROUTINE. 6**

8. **CHOOSE MENU UP OR MENU DOWN TO CHANGE SENSOR ..... 2 OR 3**

At this stage of the procedure the boom length display will indicate the extension value that you entered. After completion of Command 05, main boom radius/moment, it will display boom length. Retract the boom and continue the procedure.

SECTION 10.4.6 COMMAND 04 - SWING ZERO

THIS ROUTINE WILL **ONLY** BE REQUIRED ON MODELS THAT HAVE SWING POTENTIOMETERS.

ZERO

For **all** crane models (lattice and hydraulic or truck and all terrain) the datum for the zero of the potentiometer is
IN LINE OVER THE FRONT OF THE CARRIER.

DIRECTION

Swing direction is similar to a compass. Swinging to the right will increase the readings and swinging to the left will decrease the readings. If the swing potentiometer is electrically connected in such a way that its output is in the wrong direction, this can be accounted for during this procedure by using the direction command to change the displayed direction.

Calibrate the swing potentiometer, as shown below.

COMMAND 04 SWING POT ZERO

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.
Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step
when ENTERING or EXITING a COMMAND
and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. **ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.**
1. **CHOOSE MENU UP OR MENU DOWN AND GO TO 04 SWING POT ..... 2 OR 3**
2. **START 04 SWING POT 1**
3. **CHOOSE MENU UP OR MENU DOWN AND GO TO ZERO (IF NOT ALREADY THERE) ..... 2 OR 3**
4. **SET SLEW ZERO 1**
   NOTE: OVER FRONT OF CARRIER, THE DISPLAY WILL READ: ZERO = XXX.
5. **EXIT 3**

SECTION 10.4.7 COMMAND 04 - SWING DIRECTION

COMMAND 04 SWING POT DIRECTION

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

0. ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE.
REFER TO PAGE 69.

1. CHOOSE MENU UP OR DOWN AND GO TO 04 SWING POT 2 OR 3

2. START 04 SWING POT 1

3. CHOOSE DIRECTION..... 2 OR 3
THE CENTER DISPLAY WILL READ (+ OR -).

4. ROTATE THE UPPER APPROX. 10° TO THE RIGHT.

5. THE NUMBERS ON THE DISPLAY SHOULD INCREASE TO APPROX. 10°.
IF NOT, CHANGE THE DISPLAY TO REFLECT THE OPPOSITE DIRECTION..... 2

6. EXIT 3

7. EXIT THE ROUTINE..... 6

SECTION 10.4.8 COMMAND 13 - MONITOR

COMMAND 13 MONITOR

REVIEW THE SAMPLE DISPLAY SCREEN ON PAGE 68.

Use the designated arrow key (**1, 2, 3, 4, or 6**) appearing to the right of each step when ENTERING or EXITING a COMMAND and to CHOOSE, START, CONFIRM, ABORT, RESET, or ENTER an action.

Boom Moment data WG, WT, and Len-s can be viewed for each boom mode (up to 4) and each extension (up to 7). Also the Head Angle and BDC F-Factor, as well as the BDC F-Factor for the currently selected fly is also available.

0. ENTER THE CALIBRATION MODE AND CALIBRATION CODE, IF NOT ALREADY DONE. REFER TO PAGE 69.

1 CHANGE THE BOOM MODE..... 1

2. THE NEXT EXTENSION. 2

3. THE PREVIOUS EXTENSION 3

4. EXIT. 6

SECTION 10.4.9 COMMAND 15 - PRESSURE MONITOR

Command 15 is also a monitor function. This function allows the operator to view information on the system pressure channels. There is no action required on this screen except for the exit key (6).

COMMAND 15 PRESSURE
AVAILABLE INFORMATION
CURRENT SYSTEM TEMPERATURE
PISTON SIDE HYDRAULIC PRESSURE
ROD SIDE HYDRAULIC PRESSURE
NETT PRESSURE (THE DIFFERENCE BETWEEN PISTON AND ROD SIDE PRESSURES SCALED BY THE CYLINDER GEOMETRY.)